

FICHE  
Introduction to diffusion process

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## Contents

<b>1</b>	<b>Introduction</b>	<b>2</b>
1.1	Brownian motion . . . . .	2
1.2	Stochastic integral . . . . .	2
1.3	Girsanov theorem . . . . .	3
1.4	Itô's formula . . . . .	3
<b>2</b>	<b>Brownian motion</b>	<b>3</b>
2.1	Definition and first properties . . . . .	3
2.2	Markov property . . . . .	4
2.3	Semi-group of the Brownian motion . . . . .	6
<b>3</b>	<b>Continuous-time martingale</b>	<b>6</b>
3.1	Progressive processes . . . . .	6
3.2	Stopping time . . . . .	6
3.3	Continuous time martingale . . . . .	7
3.4	Convergence and optimal stopping theorem . . . . .	7
3.5	Example: Brownian motion . . . . .	8
<b>4</b>	<b>Continuous semimartingales</b>	<b>8</b>
4.1	Finite variation processes . . . . .	8
4.2	Continuous local martingales . . . . .	9
4.3	Quadratic variation . . . . .	10
4.4	Continuous semimartingale . . . . .	11
<b>5</b>	<b>Stochastic integral</b>	<b>11</b>
5.1	Integration for bounded integral in $L^2$ . . . . .	11
5.2	Integration for continuous semimartingales . . . . .	12
<b>6</b>	<b>Itô's formula and applications</b>	<b>13</b>
6.1	Itô's formula . . . . .	13
6.2	Exponential semimartingale . . . . .	14
6.3	Levy's characterization of the Brownian motion . . . . .	14
6.4	Dambis–Dubing–Schwarz Theorem . . . . .	15
6.5	Examples: multidimensional brownian motion . . . . .	15
6.6	Burkholder–Davis–Gundy inequality . . . . .	16
6.7	Martingales of a brownian filtration . . . . .	16
6.8	Girsanov theorem . . . . .	17
<b>7</b>	<b>Stochastic differential equations</b>	<b>17</b>
7.1	Strong and weak solutions . . . . .	17

# 1 Introduction

This introduction deliberately is incomplete from a mathematical point of view. Its aim is just to introduce some notions on stochastic calculus without being rigorous at all.

## 1.1 Brownian motion

Let us consider a set of r.v. in  $\mathbb{R}$ ,  $X_t$  is the value at time  $t$ . Between the times  $t$  and  $t+h$  with  $h > 0$ ,

$$\Delta X_t^h := X_{t+h} - X_t \quad (1.1)$$

$$= H_t \varepsilon_t^h. \quad (1.2)$$

This is the fundamental hypothesis, when  $h$  is small  $\Delta X_t^h$  is the product of  $H_t$  which is a continuous function observable at time  $t$ , and  $\varepsilon_t^h$  r.v. independent from all that happen until  $t$  and s.t. its law only depends on  $h$ .

*Remark.* This assumption is quite natural if  $X_t$  is deterministic then with  $H_t$  is its derivative and  $\varepsilon_t^h = h$ ; and you find the Taylor expansion.

Let's take  $h = h_1 + h_2$  with  $h_1, h_2 > 0$ , then

$$X_{t+h} = X_{t+h_1} + H_{t+h_1} \varepsilon_{t+h_1}^{h_2} \quad (1.3)$$

$$= X_t + \underbrace{H_t \varepsilon_t^{h_1} + H_{t+h_1} \varepsilon_{t+h_1}^{h_2}}_{H_t \varepsilon_t^h}. \quad (1.4)$$

And with  $h_1 < h$  very small by continuity we have  $H_{t+h_1} \approx H_t$ , so we deduce

$$\varepsilon_t^h \approx \varepsilon_t^{h_1} + \varepsilon_{t+h_1}^{h_2}. \quad (1.5)$$

By iterating,

$$\varepsilon_t^h \approx \varepsilon_t^{\frac{h}{n}} + \varepsilon_{t+\frac{h}{n}}^{\frac{h}{n}} + \dots + \varepsilon_{t+\frac{(n-1)h}{n}}^{\frac{h}{n}}, \quad (1.6)$$

so  $\varepsilon_t^h$  is the sum of  $n$  r.v. of same law, by the central limit theorem  $\varepsilon_t^h$  follows a normal law. We note  $m_h$  its mean and  $\sigma_h^2$  its variance. With (1.5) we deduce

$$\begin{cases} m_{h_1+h_2} = m_{h_1} + m_{h_2} \\ \sigma_{h_1+h_2}^2 = \sigma_{h_1}^2 + \sigma_{h_2}^2 \end{cases} \quad (1.7)$$

$$\Leftrightarrow \begin{cases} m_h = bh \\ \sigma_h^2 = \sigma^2 h \end{cases}, \quad b \in \mathbb{R}, \sigma \geq 0 \quad (1.8)$$

$$\Leftrightarrow \varepsilon_t^h = bh + \sigma(B_{t+h} - B_t). \quad (1.9)$$

where  $(B_t, t \geq 0)$  is a brownian motion.

**Definition 1.1** (Brownian motion). Continuous set of r.v. where each r.v. is gaussian, s.t.  $B_t \sim \mathcal{N}(0, t)$  and  $B_{t+h} - B_t$  is independent from  $(B_s, s \in [0, t])$ .

We then have with this definition,

$$X_{t+h} = X_t + H_t(bh + \sigma(B_{t+h} - B_t)). \quad (1.10)$$

If  $\sigma = 0$ , we simply have the differential equation  $\frac{dX_t}{dt} = bH_t$ , i.e.

$$X_t = X_0 + \int_0^t bH_s ds. \quad (1.11)$$

Else if  $\sigma > 0$ ,

$$X_t = X_0 + \int_0^t bH_s ds + \underbrace{\int_0^t \sigma H_s dB_s}_{\text{stochastic integral}}. \quad (1.12)$$

## 1.2 Stochastic integral

Here  $(H_t, t \geq 0)$  is a continuous process, we also assume that for all  $t$ ,  $H_t$  is observable. And it is very important that  $(B_{t+h} - B_t, h > 0)$  and  $(H_s, B_s, s \in [0, t])$  are independent.

We now want to give a sense to the stochastic integral  $\int_0^t H_s dB_s$ . Let us begin with the simple case where the function  $t \mapsto H_t$  is a floor function, i.e.

$$H_t := \sum_{i=1}^n H_{t_i} \mathbb{1}_{[t_i, t_{i+1}]}(t).$$

We then define its stochastic integral,

$$\int_0^t H_s dB_s \triangleq \sum_{i=1}^n H_{t_i} (B_{t_{i+1} \wedge t} - B_{t_i \wedge t}). \quad (1.13)$$

**Lemma 1.1.** Let  $\xi_i$  and  $\eta_i$ ,  $i \in \llbracket 1, n \rrbracket$ , square integrable r.v. s.t. for all  $i$ ,  $\mathbb{E}[\eta_i] = 0$  and  $\eta_i$  is independent from  $(\xi_j, \eta_k, j \in \llbracket 1, i \rrbracket, k \in \llbracket 1, i \rrbracket)$ . Then,

$$(i) \mathbb{E}[\sum_{i=1}^n \xi_i \eta_i] = 0;$$

$$(ii) \mathbb{E}\left[\left(\sum_{i=1}^n \xi_i \eta_i\right)^2\right] = \sum_{i=1}^n \mathbb{E}[\xi_i^2] \mathbb{E}[\eta_i^2].$$

*Proof.* For (i).

$$\begin{aligned} \mathbb{E}\left[\sum_{i=1}^n \xi_i \eta_i\right] &= \sum_{i=1}^n \mathbb{E}[\xi_i \eta_i], \quad (\text{linearity}) \\ &= \sum_{i=1}^n \mathbb{E}[\xi_i] \underbrace{\mathbb{E}[\eta_i]}_{=0}, \quad \xi_i \perp \eta_i \end{aligned}$$

For (ii).

$$\begin{aligned} \mathbb{E}\left[\left(\sum_{i=1}^n \xi_i \eta_i\right)^2\right] &= \mathbb{E}\left[\sum_{i=1}^n (\xi_i \eta_i)^2 + 2 \sum_{1 \leq i < j \leq n} \xi_i \xi_j \eta_i \eta_j\right] \\ &= \sum_{i=1}^n \mathbb{E}[\xi_i^2] \mathbb{E}[\eta_i^2] \\ &\quad + 2 \sum_{1 \leq i < j \leq n} \mathbb{E}[\xi_i \xi_j \eta_i \eta_j] \underbrace{\mathbb{E}[\eta_j]}_{=0}. \end{aligned}$$

□

**Lemma 1.2.** *Let  $(H_t, t \geq 0)$  be a constant piecewise process. If  $\mathbb{E}[H_s^2] < \infty$ , then for all  $t \geq 0$ ,*

$$(i) \mathbb{E} \left[ \int_0^t H_s \, dB_s \right] = 0 ;$$

$$(ii) \mathbb{E} \left[ \left( \int_0^t H_s \, dB_s \right)^2 \right] = \mathbb{E} \left[ \int_0^t H_s^2 \, ds \right].$$

*Proof.* Write the integral with the definition (1.13) then take  $\xi_i := H_{t_i}$  and  $\eta_i := B_{t_{i+1} \wedge t} - B_{t_i \wedge t}$  from Lemma 1.1.  $\square$

We can then extend the stochastic integral to other process as each process can be written as the limit of constant piecewise processes.

### 1.3 Girsanov theorem

**Proposition 1.3.** *Let  $r > 0$  and  $f \in L^2([0, r], ds)$ , then for all  $t \in [0, r]$ ,  $\int_0^t f(s) \, dB_s \sim \mathcal{N} \left( 0, \int_0^t f^2(s) \, ds \right)$ .*

*Proof.*  $\exists (f_n), f_n := \sum_{i=0}^{p_n-1} \alpha_i^n \mathbb{1}_{[t_{i+1}^n, t_i^n[}$  and  $f_n \rightarrow f$  in  $L^2([0, r], ds)$ . We saw that  $\int_0^t f_n(s) \, dB_s \rightarrow \int_0^t f(s) \, dB_s$  in  $L^2(\Omega)$ . And  $\int_0^t f_n(s) \, dB_s = \sum_{i=1}^{p_n} \alpha_i^n (B_{t_{i+1}^n \wedge t} - B_{t_i^n \wedge t})$  follows the normal law  $\mathcal{N} \left( 0, \int_0^t f_n(s)^2 \, ds \right)$ .  $\square$

Let us note

$$Z := \exp \left( \int_0^r f(s) \, dB_s - \frac{1}{2} \int_0^r f(s)^2 \, ds \right).$$

And let us define the probability  $\mathbb{Q}$  on  $(\Omega, \mathcal{F})$  by,

$$\mathbb{Q} = \mathbb{E}[Z \mathbb{1}_A] = \int_{\Omega} \mathbb{1}_A Z \, d\mathbb{P}, \quad A \in \mathcal{F}.$$

Then for all r.v.  $X$ ,

$$\mathbb{E}_{\mathbb{Q}}[X] = \int_{\Omega} X \, d\mathbb{Q} = \int_{\Omega} XZ \, d\mathbb{P} = \mathbb{E}[XZ].$$

**Theorem 1.4** (Girsanov's theorem). *The process defined by*

$$\tilde{B}_t := B_t - \int_0^t f(s) \, ds,$$

*is a brownian motion on  $\mathbb{Q}$ .*

### 1.4 Itô's formula

**Theorem 1.5.** *Let  $t > 0$  and  $0 =: t_0^n < \dots < t_{p_n}^n := t$  a set of subdivisions of  $[0, t]$  where the interval  $\lim_{n \rightarrow \infty} \max_{0 \leq i \leq p_n-1} (t_{i+1}^n - t_i^n) = 0$ . Then,*

$$\sum_{i=0}^{p_n-1} \left( B_{t_{i+1}^n} - B_{t_i^n} \right)^2 \xrightarrow[n \rightarrow \infty]{L^2} t$$

*Proof.* We just have to see that for all  $f : \mathbb{R} \rightarrow \mathbb{R}$  bounded measurable function,

$$\Sigma_n := \sum_{i=0}^{p_n-1} f(B_{t_i^n}) \left( (B_{t_{i+1}^n} - B_{t_i^n})^2 - (t_{i+1}^n - t_i^n) \right) \xrightarrow{L^2} 0$$

We will use the Lemma 1.1 with  $\xi_i := f(B_{t_i^n})$  and  $\eta_i := (B_{t_{i+1}^n} - B_{t_i^n})^2 - (t_{i+1}^n - t_i^n)$ .

$$\mathbb{E}[\Sigma_n^2] = \sum_{i=0}^{p_n-1} \mathbb{E}[f^2(B_{t_i^n})] \mathbb{E}[\eta_i^2],$$

and  $\eta_i$  has the same law as  $(t_{i+1}^n - t_i^n)(B_1^2 - 1)$  and  $\mathbb{E}[(B_1^2 - 1)^2] = 2$  as  $(B_1^2 - 1) \sim \chi^2(1)$ . We then note  $c := \sup_{x \in \mathbb{R}} 2f^2(x) < \infty$ ,

$$\begin{aligned} \mathbb{E}[\Sigma_n^2] &\leq c \sum_{i=0}^{p_n-1} (t_{i+1}^n - t_i^n)^2 \\ &\leq c \max_{0 \leq k \leq p_n-1} (t_{k+1}^n - t_k^n) \sum_{i=0}^{p_n-1} (t_{i+1}^n - t_i^n) \\ &\leq c t \max_{0 \leq k \leq p_n-1} (t_{k+1}^n - t_k^n) \xrightarrow[n \rightarrow \infty]{} 0 \end{aligned}$$

$\square$

**Theorem 1.6** (Itô's formula). *If  $f : \mathbb{R} \rightarrow \mathbb{R}$  is in  $\mathcal{C}^2$  then,*

$$f(B_t) = f(B_0) + \int_0^t f'(B_s) \, dB_s + \frac{1}{2} \int_0^t f''(B_s) \, ds.$$

**Theorem 1.7** (Itô's formula). *If  $f : \mathbb{R}_+ \times \mathbb{R} \rightarrow \mathbb{R}$  is in  $\mathcal{C}^{1,2}$  then,*

$$\begin{aligned} f(t, B_t) &= f(0, B_0) + \int_0^t \frac{\partial f}{\partial t}(s, B_s) \, ds \\ &\quad + \int_0^t \frac{\partial f}{\partial x}(s, B_s) \, dB_s + \frac{1}{2} \int_0^t \frac{\partial^2 f}{\partial x^2}(s, B_s) \, ds. \end{aligned}$$

## 2 Brownian motion

### 2.1 Definition and first properties

We work in the probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  that is complete, i.e. that  $\mathcal{F}$  contains all the  $\mathbb{P}$ -negligible sets. We call random processes all sets of random variables.

**Definition 2.1** (Brownian motion).  $(B_t, t \geq 0)$  is a Brownian motion (real and null in 0) if:

- (i)  $t \mapsto B_t$  (the path) is a.s. continuous on  $\mathbb{R}_+$ .
- (ii)  $B_0 = 0$  a.s.
- (iii)  $\forall n \geq 2, \forall 0 \leq t_1 \leq \dots \leq t_n, B_{t_n} - B_{t_{n-1}}, \dots, B_{t_2} - B_{t_1}, B_{t_1}$  are independant.
- (iv)  $\forall t \geq s \geq 0, B_t - B_s \sim \mathcal{N}(0, t - s)$ .

*Remark.* The Brownian motion is a process with independent increase (iii) and stationary (iv), i.e. it is a Levy process.

**Definition 2.2** (Gaussian process).  $(X_t, t \in \mathbf{T})$  is a Gaussian process if for all  $n \geq 1$  and for all  $(t_1, \dots, t_n) \in \mathbf{T}^n$ ,  $(X_{t_n}, \dots, X_{t_1})$  is a Gaussian vector.

**Proposition 2.1.**  $(X_t, t \geq 0)$  is a brownian motion iff a.s.  $t \mapsto X_t$  is continuous on  $\mathbb{R}_+$  and  $(x_t, t \geq 0)$  is a centred gaussian process of covariance  $\text{Cov}(X_t, X_s) = t \wedge s, \forall s, t \geq 0$ .

*Proof.* “ $\Rightarrow$ ”. For all  $0 \leq t_1 \leq \dots \leq t_n$ ,  $X_{t_n} - X_{t_{n-1}}, \dots, X_{t_2} - X_{t_1}, X_{t_1}$  are Gaussian and independant r.v. so  $(X_{t_n} - X_{t_{n-1}}, \dots, X_{t_2} - X_{t_1}, X_{t_1})$  is a Gaussian vector, so  $(X_1, \dots, X_n)$  is a centred Gaussian vector.

For all  $t \geq s \geq 0$ ,

$$\begin{aligned} \text{Cov}(X_t, X_s) &\triangleq \mathbb{E}[X_t X_s] - \underbrace{\mathbb{E}[X_t] \mathbb{E}[X_s]}_{=0} \\ &= \underbrace{\mathbb{E}[(X_t - X_s)] \mathbb{E}[X_s]}_{=0} + \mathbb{E}[X_s^2] \\ &= \mathbb{E}[(X_s - X_0)^2] = \text{Var}[X_s - X_0] = s - 0. \end{aligned}$$

“ $\Leftarrow$ ”. (ii).  $\text{Var}[X_0] = \mathbb{E}[X_0^2] = 0$  and  $\mathbb{E}[X_0] = 0$ .

(iii).  $\forall 0 \leq t_1 \leq \dots \leq t_n$ ,  $(X_{t_1}, \dots, X_{t_n})$  is a gaussian vector, so  $(X_{t_1}, X_{t_2} - X_{t_1}, \dots, X_{t_n} - X_{t_{n-1}})$  is also a Gaussian vector. To show the independence we just have to show that the covariance is null. For all  $1 \leq i < j \leq n$ ,

$$\begin{aligned} C &:= \text{Cov}(X_{t_i} - X_{t_{i-1}}, X_{t_j} - X_{t_{j-1}}) \\ &= \text{Cov}(X_{t_i} - X_{t_j}) - \text{Cov}(X_{t_{i-1}} - X_{t_j}) \\ &\quad - \text{Cov}(X_{t_i} - X_{t_{j-1}}) + \text{Cov}(X_{t_{i-1}} - X_{t_{j-1}}) \\ &= t_i - t_{i-1} - t_i + t_{i-1} = 0. \end{aligned}$$

(iv). For all  $t \geq s \geq 0$ ,  $X_t - X_s$  is a centred Gaussian r.v. and,

$$\begin{aligned} \text{Var}[X_t - X_s] &= \text{Var}[X_t] + \text{Var}[X_s] - 2\text{Cov}[X_t, X_s] \\ &= t + s - 2s = t - s. \end{aligned}$$

□

**Theorem 2.2** (Wiener). *The brownian motion exists.*

*Proof.*

□

**Proposition 2.3.** *If  $B_t$  is a Brownian motion, then the following processes are also:*

- (i)  $X_t = -B_t$ .
- (ii)  $X_t = \frac{1}{t} B_{\frac{1}{t}}$ .
- (iii)  $a > 0, X_t = \frac{1}{\sqrt{a}} B_{at}$ .
- (iv)  $s \geq 0, X_t = B_{t+s} - B_s$ .
- (v)  $r > 0, X_t = B_r - B_{r-t}$ , avec  $t \in [0, r]$ .

**Example 2.1** (Brownian bridge). Let  $B$  be a Brownian motion, we define  $b_t := B_t - tB_1$  with  $t \in [0, 1]$ . This is a centred Gaussian process with covariance  $s \wedge t - st$ .

- $(b_t, t \in [0, 1]) \perp\!\!\!\perp B_1$ .
- If  $(b_t, t \in [0, 1])$  is a Brownian bridge then  $(b_{1-t}, t \in [0, 1])$  also.
- If  $(b_t, t \in [0, 1])$  is a Brownian bridge then  $B_t := (1+t)b_{\frac{t}{1+t}}$  is a Brownian motion.

Note that  $b_t = (1-t)B_{\frac{t}{1-t}}$ .

**Example 2.2.** We have  $\lim_{t \rightarrow 0} B_t = 0$ , a.s. By inverting time,

$$\lim_{t \rightarrow \infty} \frac{B_t}{t} = 0.$$

**Theorem 2.4** (Lévy). *Let  $t > 0$  and  $0 =: t_0^n < \dots < t_{p_n}^n := t$  a set of subdivisions of  $[0, t]$  where the interval  $\max_{0 \leq i \leq p_n-1} (t_{i+1}^n - t_i^n) \xrightarrow[n \rightarrow \infty]{} 0$ . Then,*

$$\sum_{i=0}^{p_n-1} \left( B_{t_{i+1}^n} - B_{t_i^n} \right)^2 \xrightarrow[n \rightarrow \infty]{} t.$$

*See the proof after Theorem 1.5.*

## 2.2 Markov property

We denote by  $(\Omega, \mathcal{F}, \mathbb{P})$  a complete probability space. Define  $(\mathcal{F}_t, t \geq 0)$  a filtration, i.e. a growing set of sub-tributes from  $\mathcal{F}$ . For all  $0 \leq s \leq t$ :

$$\mathcal{F}_0 \subset \mathcal{F}_s \subset \mathcal{F}_t \subset \mathcal{F}.$$

**Example 2.3.** Let  $(X_t, t \geq 0)$  be a stochastic process and define for all  $t \geq 0$ ,

$$\mathcal{F}_t := \sigma(X_s, s \in [0, t]).$$

Then  $(\mathcal{F}_t)$  is a filtration, and it is called the canonical filtration of the process  $X$ .

We say that  $(B_t, t \geq 0)$  is a  $(\mathcal{F}_t)$ -Brownian motion if:

- (i)  $\forall t \geq 0, B_t$  is  $\mathcal{F}_t$ -measurable (adapted) ;
- (ii)  $\forall s \geq 0, (B_{t+s} - B_s, t \geq 0)$  is a Brownian motion independent from  $\mathcal{F}_s$ .

**Theorem 2.5** (Simple Markov property). *We note  $B$  a Brownian motion and  $(\mathcal{F}_t)$  its associated canonical filtration, then  $B$  is a  $(\mathcal{F}_t)$ -Brownian motion.*

*In other words, for all  $s \geq 0, (B_{t-s} - B_s, t \geq 0) \perp\!\!\!\perp \sigma(B_u, u \in [0, s])$ .*

*Proof.* We just have to show the independence, i.e. that the vectors  $(B_{t_1+s} - B_s, \dots, B_{t_n+s} - B_s), (B_{s_1}, \dots, B_{s_n})$  are independent for all  $0 \leq t_1 < \dots < t_n, 0 \leq s_1 < \dots < s_n \leq s$ .

We have  $\text{Cov}(B_{t_i+s} - B_s, B_{s_j}) = \text{Cov}(B_{t_i+s}, B_{s_j}) - \text{Cov}(B_s, B_{s_j}) = s_j - s_j = 0$ . And  $(B_{t_1+s} - B_s, \dots, B_{t_n+s} - B_s, B_{s_1}, \dots, B_{s_n})$  is a gaussian vector, so the two previous vectors are independent. □

Let  $(\mathcal{F}_t)$  be a filtration. For all  $t \geq 0$  we note

$$\mathcal{F}_{t+} := \bigcap_{u>t} \mathcal{F}_u.$$

It is clear that it is also a filtration.

**Theorem 2.6** (The 0–1 law of Blumenthal). *Let  $B$  be a Brownian motion and  $(\mathcal{F}_t)$  its associated canonical filtration. Then for all  $A \in \mathcal{F}_{0+}$ ,  $\mathbb{P}(A) = 0$  or  $1$ .*

*Proof.* Let us first show that  $B$  is a  $(\mathcal{F}_{t+})$ -Brownian motion. As previously we just have to show the independence (the other points are clear). So we have to show that, for  $A \in \mathcal{F}_{s+}$ ,  $0 \leq t_1 < \dots < t_n$  and  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  bounded and continuous:

$$\mathbb{E}[\mathbb{1}_A F(B_{t_1+s} - B_s, \dots, B_{t_n+s} - B_s)] = \mathbb{P}(A) \mathbb{E}[\mathbb{1}_A F(B_{t_1+s}, \dots, B_{t_n+s})]. \quad (2.1)$$

Let  $\varepsilon > 0$ , the process  $t \mapsto B_{t+s+\varepsilon} - B_{s+\varepsilon}$  is independent from  $\mathcal{F}_{s+\varepsilon}$  and *a fortiori*  $\mathcal{F}_{s+}$ . So,

$$\mathbb{E}[\mathbb{1}_A F(B_{t_1+s+\varepsilon} - B_{s+\varepsilon}, \dots, B_{t_n+s+\varepsilon} - B_{s+\varepsilon})] = \mathbb{P}(A) \mathbb{E}[\mathbb{1}_A F(B_{t_1+s+\varepsilon}, \dots, B_{t_n+s+\varepsilon})].$$

By  $\varepsilon \rightarrow 0$ , an argument of continuity and the dominated convergence theorem we obtain (2.1).

So we have that  $\mathcal{F}_{0+}$  is independent from  $\sigma(B_t, t \geq 0)$ . If  $A \in \mathcal{F}_{0+} = \bigcap_{u>0} \mathcal{F}_u \subset \sigma(B_t, t \geq 0)$ , then  $A \perp\!\!\!\perp A$  and  $\mathbb{P}\{A\} = \mathbb{P}\{A\}^2$ .  $\square$

**Example 2.4.** Let  $\tau := \inf\{t > 0 : B_t > 0\}$ , then  $\tau = 0$  a.s. Indeed,

$$\{\tau = 0\} = \bigcap_{\substack{t \in [0, \varepsilon] \\ t \in \mathbb{Q}}} \left\{ \sup_{\substack{s \in [0, t] \\ s \in \mathbb{Q}}} B_s > 0 \right\}, \quad \forall \varepsilon > 0$$

So  $\{\tau = 0\} = \bigcap_{\varepsilon>0} \mathcal{F}_\varepsilon = \mathcal{F}_{0+}$ , we now know that  $\mathbb{P}\{\tau = 0\} = 0$  or  $1$ . For all  $t \geq 0$ ,  $\mathbb{P}\{\tau \leq t\} \geq \mathbb{P}\{B_t > 0\} = \frac{1}{2}$  and  $\mathbb{P}\{\tau \leq t\} = \lim_{\varepsilon \rightarrow 0} \downarrow \mathbb{P}\{\tau \leq t\} \geq \frac{1}{2}$ , then  $\tau = 0$  a.s.

By time inversion we also see that  $\{t > 0 : B_t = 0\}$  is non bounded a.s.

Let  $(\mathcal{F}_t)$  be a filtration, we define

$$\mathcal{F}_\infty := \sigma(\mathcal{F}_t, t \geq 0),$$

the tiniest tribe that contains all the elements of the tribes  $\mathcal{F}_t$ .

**Definition 2.3** (Stopping time). The application  $T : \Omega \rightarrow \mathbb{R}_+ \cup \{\infty\}$  is a stopping time if for all  $t \geq 0$ ,  $\{T \leq t\} \in \mathcal{F}_t$ .

**Example 2.5.** The constant  $T = t$  is a stopping time. And  $T_a := \inf\{t > 0 : B_t = a\}$  is also a stopping time, indeed  $\{T_a \leq t\} = \{\sup_{0 \leq s \leq t} B_s = a\} \in \mathcal{F}_t$ .

**Definition 2.4.** Let  $T$  be a stopping time. The tribe of previous events to  $T$  is

$$\mathcal{F}_T := \{A \in \mathcal{F}_\infty : \forall t \geq 0, \cap\{T \leq t\} \in \mathcal{F}_t\}.$$

**Theorem 2.7** (Strong Markov property). *We note  $B$  a Brownian motion and  $(\mathcal{F}_t)$  its associated canonical filtration. Let  $T$  be a stopping time. Conditionally to  $\{T < \infty\}$ , the process  $(B_{T+t} - B_T, t \geq 0)$  is a Brownian motion independent from  $(\mathcal{F}_T)$ .*

*Proof.*  $\square$

**Theorem 2.8** (Reflexivity). *Let  $B$  be a Brownian motion. With  $t \geq 0$ , we note  $S_t := \sup_{s \in [0, t]} B_s$ . Then,*

$$\mathbb{P}\{S_t \geq a, B_t \leq b\} = \mathbb{P}\{B_t \geq 2a - b\}.$$

for all  $a \geq 0, b \leq a$ .

In particular for all fixed  $t$ ,  $S_t \sim |B_t|$ .

*Remark.* It is just for  $t$  fixed, the equality in law between  $(S_t, t \geq 0)$  and  $(|B_t|, t \geq 0)$  is false.

*Proof.*

$$\begin{aligned} \mathbb{P}\{S_a \geq t, B_t \leq b\} &= \mathbb{P}\{T_a \leq t, B_t \leq t\} \\ &= \mathbb{P}\{T_a \leq t, \tilde{B}_{t-T_a} \leq b - a\}, \\ &\quad \tilde{B}_s := B_{s+T_a} - B_{T_a} \\ &= \mathbb{P}\{(T_a, \tilde{B}) \in A_t\}, \end{aligned}$$

where  $A_t := \{(u, x) \in \mathbb{R}_+ \times \mathbb{R}, 0 \leq u \leq t, x(t-u) \leq b-a\}$ . We have  $P_{(T_a, \tilde{B})} = P_{T_a} \otimes P_{\tilde{B}}$  as  $T_a \perp\!\!\!\perp \tilde{B}$ . And  $\tilde{B} \sim -\tilde{B}$ , so,

$$\begin{aligned} \mathbb{P}\{S_a \geq t, B_t \leq b\} &= \mathbb{P}\{(T_a, -\tilde{B}_t) \in A_t\} \\ &= \mathbb{P}\{T_a \leq t, -\tilde{B}_{t-T_a} \leq b-a\} \\ &= \mathbb{P}\left\{ \underbrace{T_a \leq t}_{S_t \geq a}, \underbrace{-(B_t - a) \leq b-a}_{B_t \geq 2a-b} \right\} \\ &= \mathbb{P}\{B_t \geq 2a - b\}, \quad \text{as } 2a - b \geq a. \end{aligned}$$

To prove that they have the same law,

$$\begin{aligned} \mathbb{P}\{S_a \geq a\} &= \mathbb{P}\{S_a \geq a, B_t \leq a\} + \mathbb{P}\{S_a \geq a, B_t > a\} \\ &= \mathbb{P}\{B_t \geq 2a - a\} + \mathbb{P}\left\{ \underbrace{B_t}_{=-B_t} \geq a \right\} \\ &= \mathbb{P}\{|B_t| \geq a\}. \end{aligned}$$

$\square$

**Corollary.** *For all  $t > 0$ , the density of  $(S_t, B_t)$  is*

$$\frac{2(2a-b)}{\sqrt{2at^3}} \exp\left(-\frac{(2a-b)^2}{2t}\right) \mathbb{1}_{\{a>0, b<a\}}.$$

**Example 2.6.** Let  $t > 0$  and  $a > 0$ ,

$$\begin{aligned} \mathbb{P}\{T_a \leq t\} &= \mathbb{P}\{S_t \geq a\} \\ &= \mathbb{P}\{|B_t| \geq a\} \\ &= \mathbb{P}\{|\sqrt{t}B_1| \geq a\} \\ &= \mathbb{P}\left\{t \geq \frac{a^2}{|B_1|^2}\right\}. \end{aligned}$$

So  $T_a \sim \frac{a^2}{B_1^2}$

### 2.3 Semi-group of the Brownian motion

Let  $s \geq 0$  and  $f : \mathbb{R} \rightarrow \mathbb{R}_+$  measurable, we can write

$$\begin{aligned}\mathbb{E}[f(B_{t+s})|\mathcal{F}_s] &= \mathbb{E}[f(B_{t+s} - B_s + B_s)|\mathcal{F}_s] \\ &= (P_t f)(B_s),\end{aligned}$$

where for all  $x \in \mathbb{R}$ ,  $P_t f := \mathbb{E}[f(B_t + x)] = \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi t}} \exp\left(-\frac{(x-y)^2}{2t}\right) f(y) dy$ .  
 $(P_t, t \geq 0)$  is the semi-group of  $B$ . Indeed,

$$\begin{aligned}P_{t+s} f(x) &\triangleq \mathbb{E}[f(B_{t+s} + x)] \\ &= \mathbb{E}[\mathbb{E}[f(B_{t+s} + x)|\mathcal{F}_t]] \\ &= \mathbb{E}[(P_s f)(B_t + x)] \\ &= P_t(P_s f)(x).\end{aligned}$$

**Proposition 2.9** (Feller property). *Let  $f \in \mathcal{C}_0$  (continuous s.t.  $\lim_{|x| \rightarrow \infty} f(x) = 0$ ), then  $P_t f \in \mathcal{C}_0$  and  $\lim_{t \downarrow 0} P_t f = f$  uniform on  $\mathbb{R}$ .*

**Proposition 2.10** (Infinitesimal generator). *If  $f \in \mathcal{C}_c^2$  (class  $\mathcal{C}^2$  on a compact space), then  $\lim_{x \downarrow 0} \frac{P_t f(x) - f(x)}{t} = \frac{1}{2} f''(x)$ .*

There is a strong link with the heat equation. Let  $u(t, x) := P_t f(x)$ . On a  $u(0, x) = f(x)$ . If  $f$  is measurable and bounded then,

$$\frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2}.$$

## 3 Continuous-time martingale

### 3.1 Progressive processes

Let  $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$  be a filtered (probability) space. We define

$$\mathcal{F}_{t+} = \bigcap_{u>y} \mathcal{F}_u,$$

for  $t \geq 0$ .

**Definition 3.1** (Right continuity). We say that  $(\mathcal{F}_t)_{t \geq 0}$  is right continuous if  $\forall t > 0, \mathcal{F}_{t+} = \mathcal{F}_t$ .

**Definition 3.2** (Complete). We say that  $(\mathcal{F}_t)_{t \geq 0}$  is complete if  $\mathcal{F}_0$  contains all the  $\mathbb{P}$ -null sets.

**Proposition 3.1.** *We have a bunch of properties about the process  $(X_t, t \geq 0)$ :*

- (i) *it is right (respectively left) continuous if a.s.  $t \mapsto X_t$  is right (respectively left) continuous.*
- (ii) *it is adapted if  $\forall t \geq 0, X_t$  is  $\mathcal{F}_t$ -measurable ;*
- (iii) *it is progressive (or progressively measurable) if  $\forall t \geq 0, (s, \omega) \mapsto X_s(\omega)$  is measurable along  $\mathcal{B}([0, t]) \otimes \mathcal{F}_t$ .*

We have  $(X_t, t \geq 0)$  progressive  $\Rightarrow (X_t, t \geq 0)$  adapted. The reverse is generally false.

**Proposition 3.2.** *If  $(\mathcal{F}_t)$  is complete and  $(X_t, t \geq 0)$  a process in  $\mathbb{R}^d$ , adapted, right (or left) continuous, then  $(X_t, t \geq 0)$  is progressive.*

*Proof.* Let  $(X_t, t \geq 0)$  be right continuous, so  $\forall t \geq 0, \forall n \geq 1$  we set

$$X_s^{(n)} := X_{\left(\lfloor \frac{ns}{t} \rfloor + 1\right) \frac{t}{n} \wedge t},$$

with  $s \in [0, t]$ . And  $\forall s \in [0, t], X_s^{(n)} \rightarrow X_s$ . Now for all  $A \in \mathcal{B}(\mathbb{R}^d)$ ,  $\{(s, \omega) \in [0, t] \times \Omega : X_s^{(n)}(\omega) \in A\}$  can be written as

$$\bigcup_{k=1}^n \left( \left[ \frac{(k-1)t}{n}, \frac{kt}{n} \right] \times X_{\frac{kt}{n}}^{-1}(A) \right) \cup (\{t\} \times X_t^{-1}(A)).$$

Where  $X_{\frac{kt}{n}}^{-1}(A)$  is  $\mathcal{F}_{\frac{kt}{n}}$ -measurable so  $\mathcal{F}_t$ -measurable. And  $\mathcal{F}_t$  is complete so  $\mathbb{P}$ -null sets make no trouble and  $X_s$  is  $\mathcal{B}([0, t]) \otimes \mathcal{F}_t$ -measurable as limit of  $\mathcal{B}([0, t]) \otimes \mathcal{F}_t$ -measurable functions.  $\square$

Let  $A \subset \mathbb{R}_+ \times \Omega$  and  $A \in \mathcal{B}(\mathbb{R}_+) \otimes \mathcal{F}$ , is progressive if  $(x_t(\omega) := \mathbb{1}_{\{(t, \omega) \in A, t \geq 0\}})$  is a progressive process. And

- $\{A \text{ progressive}\}$  is a tribe called the progressive tribe ;
- $(X_t, t \geq 0)$  is progressive  $\Leftrightarrow (t, \omega) \mapsto X_t(\omega)$  along the progressive tribe.

### 3.2 Stopping time

Let  $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$  be a filtered space. We recall

$$\mathcal{F}_\infty := \sigma(\mathcal{F}_t, t \geq 0),$$

and that  $T : \Omega \rightarrow \mathbb{R} \cup \{\infty\}$  is a stopping time if  $\forall t \geq 0, \{T \leq t\} \in \mathcal{F}_t$ .

**Definition 3.3.** If  $T$  is a stopping a time we set

$$\mathcal{F}_T := \{A \in \mathcal{F}_\infty : A \cap \{T \leq t\} \in \mathcal{F}_t, \forall t \geq 0\}.$$

**Proposition 3.3.** *We have the following properties:*

- (i) *if  $S \leq T$  stopping times  $\Rightarrow \mathcal{F}_S \subset \mathcal{F}_T$  ;*
- (ii)  *$S, T$  stopping times  $\Rightarrow S \vee T, S \wedge T$  stopping times and  $\mathcal{F}_{S \wedge T} = \mathcal{F}_S \cap \mathcal{F}_T$  ;*
- (iii)  *$\{S \leq T\}, \{S < T\}, \{S = T\} \in \mathcal{F}_{S \wedge T}$  ;*
- (iv)  *$(\mathcal{F}_t)$  right continuous and  $T$  stopping time  $\Leftrightarrow \{T < t\} \in \mathcal{F}_t, \forall t > 0$  ;*
- (v)  *$(\mathcal{F}_t)$  right continuous and  $(T_n)$  set of stopping time  $\Rightarrow T := \inf_{n \geq 1} T_n$  stopping time and  $\mathcal{F}_T = \bigcap_{n \geq 1} \mathcal{F}_{T_n}$ .*

*Proof.* (i).  $\forall A \in \mathcal{F}_S$  we have  $A \in \mathcal{F}_\infty$  this is trivial. We just have to show that  $A \cap \{T \leq t\} \in \mathcal{F}_t$  for all  $t$ . Indeed,

$$A \cap \{T \leq t\} \in \mathcal{F}_t = \underbrace{A \cap \{S \leq t\}}_{\in \mathcal{F}_t} \cap \underbrace{\{T \leq t\}}_{\in \mathcal{F}_t}.$$

(ii). For all  $t$ ,

$$\{S \wedge T\} = \underbrace{\{S \leq t\}}_{\in \mathcal{F}_t} \cap \underbrace{\{T \leq t\}}_{\in \mathcal{F}_t},$$

so  $\{S \wedge T\} \in \mathcal{F}_t$  and it's a stopping time. We use the same proof for  $S \vee T$ .

$\mathcal{F}_{S \wedge T} \subset \mathcal{F}_S$  and  $\subset \mathcal{F}_T$  so  $\mathcal{F}_{S \wedge T} \subset \mathcal{F}_S \cap \mathcal{F}_T$ . Now let  $A \in \mathcal{F}_S \cap \mathcal{F}_T$ , and for all  $t$ ,

$$A \cap \{S \wedge T \leq t\} = \underbrace{(A \cap \{S \leq t\})}_{\in \mathcal{F}_t} \cup \underbrace{(A \cap \{T \leq t\})}_{\in \mathcal{F}_t} \in \mathcal{F}_t,$$

so  $A \in \mathcal{F}_{S \wedge T}$  and  $\mathcal{F}_{S \wedge T} \supset \mathcal{F}_S \cap \mathcal{F}_T$ .  $\square$

**Proposition 3.4.** Let  $T$  be a stopping time, for all  $n \geq 0$  set

$$T_n := \sum_{k=0}^{\infty} \frac{k}{2^n} \mathbb{1}_{\{\frac{k-1}{2^n} < T \leq \frac{k}{2^n}\}} + \infty \mathbb{1}_{\{\infty\}},$$

then  $(T_n, n \geq 1)$  is a stopping time set that converges towards  $T$ .

*Proof.* For all  $t$ ,

$$\{T_n \leq t\} = \{T < t\} \cap \underbrace{\{T_n \leq t\}}_{\in \mathcal{F}_T} \in \mathcal{F}_t.$$

So it's a stopping time.  $\square$

**Theorem 3.5.** Let  $(X_t, t \geq 0)$  be a progressive process in  $\mathbb{R}^d$  and  $T$  a stopping time. Then  $\mathbb{1}_{\{T < \infty\}} X_T$  is  $\mathcal{F}_T$ -measurable.

If furthermore  $X_t(\omega) \xrightarrow[t \rightarrow \infty]{} X_\infty(\omega) \in \mathbb{R}^d, \forall \omega \in \Omega$  then  $X_T$  is  $\mathcal{F}_T$ -measurable.

### 3.3 Continuous time martingale

Let  $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$  be a filtered space.

**Definition 3.4** (Martingale). We call  $(M_t, t \geq 0)$  a martingale (respectively submartingale, supermartingale) if

- (i)  $(M_t, t \geq 0)$  is adapted ;
- (ii)  $\forall t \geq 0, \mathbb{E}[|M_t|] < \infty$  ;
- (iii)  $\forall t \geq s \geq 0, \mathbb{E}[M_t | \mathcal{F}_s] = M_s$  a.s. (respectively  $\geq, \leq$ ).

*Remark.* It is clear that for  $(M_t, t \geq 0)$  submartingale (resp. supermartingale),  $t \mapsto \mathbb{E}[M_t]$  is growing (resp. is decreasing).

**Example 3.1.** Let  $B = (B_t, t \geq 0)$  be a  $(\mathcal{F}_t)$ -brownian motion, then the following processes are martingales

- (i)  $(B_t, t \geq 0)$  ;
- (ii)  $(B_t^2 - t, t \geq 0)$  ;
- (iii)  $(e^{\theta B_t - \frac{\theta^2}{2}t}, \text{ with } \theta \in \mathbb{R}.$

*Remark.* If  $(M_t, t \geq 0)$  is a martingale and  $f : \mathbb{R} \rightarrow \mathbb{R}$  convex s.t.  $\mathbb{E}[|f(M_t)|] < \infty$ , then  $(f(M_t), t \geq 0)$  is a submartingale.

**Theorem 3.6** (Maximal inequality). Let  $(M_t, t \geq 0)$  be a submartingale right continuous, then

$$\mathbb{P} \left\{ \sup_{s \in [0, t]} M_s > \lambda \right\} \leq \frac{\mathbb{E}[|M_t|]}{\lambda},$$

for all  $\lambda > 0, t \geq 0$ .

**Theorem 3.7** (Doob's inequality). Let  $(M_t, t \geq 0)$  be a right continuous martingale and  $p > 1 \in \mathbb{R}$ . Then

$$\left\| \sup_{s \in [0, t]} |M_s| \right\|_p \leq q \|M_t\|_p,$$

for all  $t \geq 0$ , where  $\frac{1}{p} + \frac{1}{q} = 1$ .

And consequently

$$\left\| \sup_{s \geq 0} |M_s| \right\|_p \leq q \sup_{s \geq 0} \|M_s\|_p$$

### 3.4 Convergence and optimal stopping theorem

**Theorem 3.8.** Let  $(M_t, t \geq 0)$  be right continuous submartingale s.t.  $\sup_{t \geq 0} \mathbb{E}[M_t] < \infty$  (one can show that a equivalent is  $\sup_{t \geq 0} \mathbb{E}[|M_t|] < \infty$ ) then,

$$M_\infty := \lim_{t \rightarrow \infty} M_t \text{ exists a.s.}$$

and  $\mathbb{E}[|M_\infty|] < \infty$ .

*Proof.* We define  $D \subset \mathbb{R}_+$  a countable dense space. With  $a < b \in \mathbb{R}$ ,  $N_{ab}([0, t] \cap D)$  is the number of grows of  $(M_s, s \in [0, t] \cap D)$  along  $[a, b]$ . We have

$$\begin{aligned} \mathbb{E}[N_{ab}([0, t] \cap D)] &\leq \frac{\mathbb{E}[(M_t - a)^+]}{b - a} \\ &\leq \frac{\sup_{u \geq 0} \mathbb{E}[(M_u)^+ + |a|]}{b - a} < \infty. \end{aligned}$$

Then with  $t \rightarrow \infty$  we have for all  $a < b$ ,  $N_{ab}(D) < \infty$  a.s. and so  $\lim_{t \rightarrow \infty} M_t$  exists.

Then with Fatou we verify that this limit is not  $\pm\infty$ , and finally as  $D$  is dense we have the result on  $\mathbb{R}_+$  by writing the definition of the limit.  $\square$

**Corollary.** Let  $(M_t, t \geq 0)$  be a positive right continuous supermartingale, then  $M_t \xrightarrow[t \rightarrow \infty]{a.s.} M_\infty$  and  $\mathbb{E}[M_\infty] \leq \mathbb{E}[M_0] < \infty$ .

**Theorem 3.9.** Let  $p > 1$  be a real number and  $(M_t, t \geq 0)$  a right continuous martingale s.t.  $\sup_{t \geq 0} \mathbb{E}[|M_t|^p] < \infty$ , then

$$M_t \xrightarrow[t \rightarrow \infty]{L^p \text{ a.s.}} M_\infty.$$

*Proof.*  $\square$

**Theorem 3.10.** Let  $(M_t, t \geq 0)$  be a right continuous submartingale uniformly integrable (UI), then

$$(i) \quad M_t \xrightarrow[t \rightarrow \infty]{L^1} m_\infty ;$$

$$(ii) \quad M_t \xrightarrow[t \rightarrow \infty]{a.s.} m_\infty ;$$

$$(iii) \quad \forall t \geq 0, M_t \leq \mathbb{E}[M_\infty | \mathcal{F}_t] \text{ a.s.}$$

**Theorem 3.11** (Optimal stopping theorem). Let  $(M_t, t \geq 0)$  be a right continuous submartingale and  $S \leq T$  stopping times. If (a)  $(M_t, t \geq 0)$  UI or (b)  $S \leq T$  bounded ( $\exists C < \infty$  s.t.  $T(\omega) \leq C$ , for all  $\omega \in \Omega$ ) then

$$M_S \leq \mathbb{E}[M_t | \mathcal{F}_S] \text{ a.s.}$$

And consequently  $\mathbb{E}[M_S] \leq \mathbb{E}[M_t]$ .

**Example 3.2.**  $(M_t, t \geq 0)$  a right continuous submartingale and  $S \leq T$ , bounded stopping times. Then  $\mathbb{E}[M_T | \mathcal{F}_S] \geq M_{S \wedge T}$  a.s.

Indeed,

$$\begin{aligned} \mathbb{E}[M_T | \mathcal{F}_S] &= \mathbb{E}[M_T \mathbb{1}_{\{S \leq T\}} | \mathcal{F}_S] + \mathbb{E}[M_T \mathbb{1}_{\{S > T\}} | \mathcal{F}_S] \\ &= \mathbb{E}[M_{T \vee S} \mathbb{1}_{\{S \leq T\}} | \mathcal{F}_S] + \mathbb{E}[M_{T \wedge S} \mathbb{1}_{\{S > T\}} | \mathcal{F}_S] \\ &= \mathbb{1}_{\{S \leq T\}} \underbrace{\mathbb{E}[M_{T \vee S} | \mathcal{F}_S]}_{\geq M_S} + \mathbb{1}_{\{S > T\}} \underbrace{\mathbb{E}[M_{T \wedge S} | \mathcal{F}_S]}_{= M_{S \wedge T}} \\ &\geq M_{S \wedge T}. \end{aligned}$$

**Example 3.3.**  $(M_t, t \geq 0)$  a right continuous submartingale and  $T$  stopping time, then  $(M_{T \wedge t}, t \geq 0)$  a right continuous submartingale.

Indeed for all  $t \geq 0$ ,  $M_{T \wedge t}$  is  $(\mathcal{F}_{T \wedge t})$ -measurable so  $(\mathcal{F}_t)$ -measurable. And for all  $t \geq s \geq 0$ ,  $\mathbb{E}[M_{T \wedge t} | \mathcal{F}_s] \geq M_{(T \wedge t) \wedge s} = M_{T \wedge s}$ .

### 3.5 Example: Brownian motion

**Example 3.4.** Let  $T_a := \inf\{t \geq 0 : B_t = a\}$ . We know that  $(M_t := e^{\theta B_t - \frac{\theta^2}{2}t}, t \geq 0)$  is a martingale. For  $a > 0$ ,  $(M_{T_a \wedge t}, t \geq 0)$  continuous bounded martingale, so UI. And so  $\mathbb{E}[M_{T_a}] = \mathbb{E}[M_0] = 1$  with the optimal stopping theorem. On the other hand  $\mathbb{E}[M_{T_a}] = \mathbb{E}[e^{\theta a - \frac{\theta^2}{2}T_a}]$  and then with  $\lambda := \frac{\theta^2}{2}$ ,

$$\mathbb{E}[e^{-\lambda T_a}] = e^{-\sqrt{2\lambda a^2}}.$$

**Example 3.5.** Let  $(X_t, Y_t)$  be Brownian motion in  $\mathbb{R}^2$  with  $X_0 = 0$  and  $Y_1 = 1$ . We are looking for the distribution of  $X_T$  with  $T := \inf\{t \geq 0 : Y_t = 0\}$ .

Let  $a \in \mathbb{R}$ ,

$$\begin{aligned} \mathbb{E}[e^{iaX_T}] &= \mathbb{E}[\mathbb{E}[e^{iaX_T} | Y_t]] \\ &= \mathbb{E}\left[e^{-\frac{a^2}{2}T}\right] \\ &= e^{-|a|}, \end{aligned}$$

i.e.  $X_T$  has a standard Cauchy distribution.

## 4 Continuous semimartingales

### 4.1 Finite variation processes

Let  $r > 0$  fixed and  $a : [0, r] \rightarrow \mathbb{R}$  a finite variation continuous function with  $a(0) = 0$ . It is variation finite if  $a = c_+ - c_-$  where  $c_\pm : [0, r] \rightarrow \mathbb{R}$  growing functions.

We can assume that  $c_\pm$  are continuous and  $c_\pm(0) = 0$ .

Let  $\mu_\pm$  be Stieltjes measures associated to  $c_\pm$ , so

$$\mu_\pm([0, t]) = c_\pm(t),$$

for all  $t \in [0, r]$ .

**Theorem 4.1** (Stieltjes). Let  $F : \mathbb{R} \rightarrow \mathbb{R}$  growing and right continuous function, then there exists a unique measure  $\mu$  on  $\mathbb{R}$  s.t.

$$\mu([a, b]) = F(b) - F(a),$$

for all  $a < b \in \mathbb{R}$ .

We can write

$$\mu := \mu_+ - \mu_-,$$

where  $\mu_\pm$  are signed measures on  $[0, r]$ . Actually this decomposition is unique and exists if  $\mu_\pm$  are orthogonal, i.e. for all  $A$  measurable  $\mu_+(A) = \mu_-(A^C) = 0$ .

We can also write

$$|\mu| := \mu_+ + \mu_-,$$

the total variation measure associated to the function  $a$ . And we have  $\mu_\pm \ll |\mu|$  (i.e.  $\forall A$  s.t.  $|\mu|(A) = 0 \Rightarrow \mu_\pm(A) = 0$ ).

**Proposition 4.2.** With the subdivisions  $0 =: t_0 < \dots < t_p := r$ ,

$$|\mu|([0, r]) = \sup_{t_i} \sum_{i=1}^p |a(t_i) - a(t_{i-1})|.$$

*Proof.*  $\square$

We still have  $a : [0, r] \rightarrow \mathbb{R}$  a finite variation continuous function with  $a(0) = 0$ , and  $f : [0, r] \rightarrow \mathbb{R}$  measurable s.t.  $\int_{[0, r]} |f| d|\mu| < \infty$ . Then we define

$$\begin{aligned} \int_0^t f(x) da(s) &:= \int_0^t f(s) \mu(ds) \\ &:= \int_0^t f(s) \mu_+(ds) - \int_0^t f(s) \mu_-(ds) \in \mathbb{R}, \end{aligned}$$



for all  $t \in [0, r]$ . And also

$$\begin{aligned} \int_0^t f(x) |da(s)| &:= \int_0^t f(s) |\mu|(ds) \\ &:= \int_0^t f(s) \mu_+(ds) + \int_0^t f(s) \mu_-(ds) \in \mathbb{R}. \end{aligned}$$

We have the triangular inequality

$$\left| \int_0^t f(s) da(s) \right| \leq \int_0^t |f(s)| |da(s)|.$$

**Lemma 4.3.** *Let  $f : [0, r] \rightarrow \mathbb{R}$  be continuous and a sequence of subdivisions of  $[0, r]$ :  $0 =: t_0^n < \dots < t_{p_n}^n := r$  from which the interval goes to 0. Then*

$$\int_0^t f(s) da(s) = \lim_{n \rightarrow \infty} \sum_{i=1}^{p_n} f(t_{i-1}^n) (a(t_i^n) - a(t_{i-1}^n)).$$

*Proof.* We define for all  $n$ ,  $f_n(s) := \sum_{i=1}^{p_n} f(t_{i-1}^n) \mathbb{1}_{]t_{i-1}^n, t_i^n]}(s)$ , so

$$\begin{aligned} \sum_{i=1}^{p_n} f(t_{i-1}^n) (a(t_i^n) - a(t_{i-1}^n)) &= \int_0^r f_n(s) da(s) \\ &\xrightarrow{n \rightarrow \infty} \int_0^r f(s) da(s), \end{aligned}$$

with dominated convergence.  $\square$

Now we can enlarge this result on  $\mathbb{R}$ .  $a : \mathbb{R}_+ \rightarrow \mathbb{R}$  is a finite variation on  $\mathbb{R}_+$  (i.e. if for all  $r > 0$ ,  $a$  is a finite variation function on  $[0, r]$ ) continuous function with  $a(0) = 0$ . Let  $f : \mathbb{R}_+ \rightarrow \mathbb{R}$  measurable s.t.  $\int_0^\infty |f(s)| |da(s)| := \sup_{r>0} \int_0^r |f(s)| |da(s)| < \infty$ . Then

$$\int_0^\infty f(s) da(s) := \lim_{r \rightarrow \infty} \int_0^r f(s) da(s).$$

Let us now define a filtered space  $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$ , with the filtration  $(\mathcal{F}_t)$  that is right continuous and complete.

**Proposition 4.4.** *Let  $(V_t, t \geq 0)$  be a continuous and adapted process, with finite variations and  $V_0 = 0$ . And  $(H_t, t \geq 0)$  a progressive process, s.t.  $\forall t > 0$ ,  $\int_0^t |H_s(\omega)| |dV_s(\omega)| < \infty$  a.s. Then,*

$$\left( \int_0^t H_s dV_s, t \geq 0 \right)$$

*is a continuous, adapted process, null in 0 and with finite variations.*

<sup>1</sup>Recall that if  $a$  is at finite variation then

$$|\mu|([0, r]) = \sup_{t_i} |a(t_i) - a(t_{i+1})|.$$

## 4.2 Continuous local martingales

We note with  $X := (X_t, t \geq 0)$ ,  $T$  a stopping time,

$$X^T := (X_{t \wedge T}, t \geq 0).$$

**Definition 4.1** (Local martingale (continuous)). We call  $M := (M_t, t \geq 0)$  a local martingale if there exists  $(T_n, n \geq 1)$  growing sequence of stopping time s.t.  $T_n \uparrow \infty$  a.s. and that for all  $n \geq 1$ ,  $M^{T_n} - M_0$  is a continuous martingale UI.

But be careful we don't know anything about  $M_t$ , especially  $\forall t, \mathbb{E}[|M_t|] \leq \infty$ .

We say that  $(T_n)$  reduces  $M$ .

*Remark.* •  $M$  if a continuous martingale  $\Rightarrow M$  is a local continuous martingale (just take  $T_n := n$ ).

- In the definition we can suppose that for all  $n$ ,  $M^{T_n} - M_0$  is a bounded martingale.
- $M$  is a local continuous martingale,  $T$  stopping time,  $\Rightarrow M^T$  local martingale.
- $(T_n)$  reduces  $M$ ,  $(S_n)$  a stopping time  $\uparrow \infty$  a.s.  $\Rightarrow (T_n \wedge S_n)$  reduces  $M$ .
- A linear combination of two local martingale is a local martingale.

**Proposition 4.5.** *We have the following properties*

- (i)  $M$  local positive continuous martingale,  $\mathbb{E}[M_0] < \infty \Rightarrow M$  supermartingale.
- (ii)  $M$  local continuous martingale s.t.  $\forall t \geq 0, \mathbb{E}[\sup_{s \in [0, t]} |M_s|] < \infty \Rightarrow M$  martingale.
- (iii)  $M$  local continuous martingale s.t.  $\mathbb{E}[\sup_{t \in [0, t]} |M_t|] < \infty \Rightarrow M$  martingale UI.

*Proof.* Let  $(T_n)$  reduce  $M$ .

(i).  $\forall n, M^{T_n} - M_0$  a martingale UI. We have  $M_0$  is  $\mathcal{F}_0$ -measurable so  $M^{T_n}$  is a martingale UI. And so for all  $t \geq s \geq 0$ ,

$$\underbrace{\mathbb{E}[M_{T_n \wedge t} | \mathcal{F}_s]}_{\substack{\text{a.s.} \\ \rightarrow M_t}} = \underbrace{M_{T_n \wedge s}}_{\substack{\text{a.s.} \\ \rightarrow M_s}}.$$

So by Fatou's Lemma,

$$\mathbb{E}[M_t | \mathcal{F}_s] \leq \liminf_{n \rightarrow \infty} \mathbb{E}[M_{T_n \wedge t} | \mathcal{F}_s] = M_s.$$

(ii).  $\forall t \geq s \geq 0, \forall A \in \mathcal{F}_s, \mathbb{E}[M_{T_n \wedge t} \mathbb{1}_A] = \mathbb{E}[M_{T_n \wedge s} \mathbb{1}_A]$ . And  $M_{T_n \wedge t} \rightarrow M_t$ , so by dominated convergence  $\mathbb{E}[M_{T_n \wedge t} \mathbb{1}_A] \rightarrow \mathbb{E}[M_t \mathbb{1}_A]$ . We have the same for the right hand side in the equality. So for all  $A \in \mathcal{F}_s$ ,

$$\begin{aligned} \mathbb{E}[M_t \mathbb{1}_A] &= \mathbb{E}[M_s \mathbb{1}_A] \\ \Rightarrow \mathbb{E}[M_t | \mathcal{F}_s] &= \mathbb{E}[M_s | \mathcal{F}_s] = M_s. \end{aligned}$$

$\square$

**Theorem 4.6.** Let  $M$  be a local continuous martingale,  $M_0 = 0$  a.s. If  $M$  is at finite variation<sup>1</sup>, then

$$\mathbb{P}\{M_t = 0, \forall t \geq 0\} = 1.$$

*Proof.*  $\square$

### 4.3 Quadratic variation

**Theorem 4.7.** Let  $M$  be a local continuous martingale, then

- (i) There exists a unique<sup>2</sup> continuous adapted growing process, null in 0, that we note  $\langle M \rangle = (\langle M \rangle_t, t \geq 0)$  s.t.  $(M_t^2 - \langle M \rangle_t, t \geq 0)$  is a local continuous martingale.
- (ii) For all  $t > 0$ , for all  $0 =: t_0^n < \dots < t_{p_n}^n := t$  sequence of subdivision of  $[0, t]$  where the intervals go to 0,

$$\sum_{i=1}^{p_n} (M_{t_i^n} - M_{t_{i-1}^n})^2 \xrightarrow[n \rightarrow \infty]{\mathbb{P}} \langle M \rangle_t.$$

*Proof.* (Unicity). Assume that  $X$  and  $Y$  satisfy the conditions of  $\langle M \rangle$ , then  $M^2 - X, M^2 - Y$  are local martingales  $\Rightarrow X - Y$ , is a local martingale with finite variation, null in 0, and with Theorem 4.6,  $\mathbb{P}\{X_t - Y_t = 0, t \geq 0\} = 1$ .  $\square$

We call  $\langle M \rangle$  the quadratic variation of  $M$ .

**Example 4.1.** Let  $B$  be a  $(\mathcal{F}_t)$ -brownian motion, then  $\langle B \rangle_t = t$ , consequence of the Levy theorem, or the fact that  $(B_t^2 - t, t \geq 0)$  is a martingale.

**Proposition 4.8.** Let  $M$  be a local continuous martingale and  $T$  a stopping time, then

$$\langle M^T \rangle = \langle M \rangle^T.$$

*Proof.* We have by definition  $(M^T)^2 - \langle M^T \rangle$  which is a local martingale, so let us just show that  $(M^T)^2 - \langle M \rangle^T$  is also a local martingale and the proof is made. For  $t \geq 0$ ,

$$(M^T)_t^2 - \langle M \rangle_t^T = M_{T \wedge t}^2 - \langle M \rangle_{T \wedge t},$$

which is a local martingale.  $\square$

**Theorem 4.9.** Let  $M$  be a local continuous martingale,  $M_0 = 0$ ,

- (i)  $\mathbb{E}[\langle M \rangle_t] < \infty, \forall t \geq 0 \Leftrightarrow M$  is square-integrable. In this case  $(M_t^2 - \langle M \rangle_t, t \geq 0)$  is a martingale null in 0.
- (ii)  $\mathbb{E}[\langle M \rangle_\infty] < \infty \Leftrightarrow M$  is a martingale s.t.  $\sup_{t \geq 0} \mathbb{E}[M_t^2] < \infty$ <sup>(3)</sup>. In this case  $(M_t^2 - \langle M \rangle_t, t \geq 0)$  is a UI martingale null in 0.

<sup>2</sup>In the sense that if  $(X_t)$  and  $(Y_t)$  follow this property then  $\mathbb{P}\{X_t = Y_t, \forall t \geq 0\} = 1$ .

<sup>3</sup>With the Doob inequality it is equivalent to have  $\mathbb{E}[\sup_{t \geq 0} M_t^2] < \infty$ .

<sup>4</sup>Finite variation.

<sup>5</sup>The process  $(X_t, t \geq 0)$  is measurable if it is progressive.

*Proof.*  $\square$

**Corollary.** Let  $M$  be a local continuous martingale,  $M_0 = 0$  a.s. Then,

$$\mathbb{P}\{\langle M \rangle_t = 0, \forall t \geq 0\} = 1 \Leftrightarrow \mathbb{P}\{M_t = 0, \forall t \geq 0\} = 1.$$

*Proof.* “ $\Leftarrow$ ” is trivial. For the other implication, assume that  $\langle M \rangle = 0$  a.s. then with (ii) of Theorem (4.9),  $M^2$  is a UI martingale, and  $\mathbb{E}[M_t^2] = \mathbb{E}[M_0^2] = 0$ .  $\square$

**Definition 4.2.** Let  $M, N$  be local continuous martingale,

$$\begin{aligned} \langle M, N \rangle &:= \frac{1}{4} (\langle (M + N) \rangle_t - \langle (M - N) \rangle_t) \\ &= \frac{1}{2} (\langle (M + N) \rangle_t - \langle M \rangle_t - \langle N \rangle_t). \end{aligned}$$

And in particular,  $\langle M, M \rangle = \langle M \rangle$ .

**Proposition 4.10.** (i)  $\langle M, N \rangle$  is the unique continuous adapted process at f.v.<sup>4</sup>, null in 0, s.t.  $MN - \langle M, N \rangle$  is a local martingale.

- (ii)  $(M, N) \mapsto \langle M, N \rangle$  is a symmetrical bi-linear application.
- (iii) For all  $t \geq 0, 0 =: t_0^n < \dots < t_{p_n}^n$ , where the intervals go to 0,

$$\sum_{i=1}^{p_n} (M_{t_i^n} - M_{t_{i-1}^n}) (N_{t_i^n} - N_{t_{i-1}^n}) \xrightarrow[n \rightarrow \infty]{\mathbb{P}} \langle M, N \rangle_t.$$

- (iv) Let  $T$  be a stopping time,  $\langle M, N \rangle^T = \langle M^T, N \rangle = \langle M, N^T \rangle = \langle M^T, N^T \rangle$ .

*Proof.* If we use the property of polarisation, i.e.  $ab = \frac{1}{4} ((a+b)^2 - (a-b)^2)$ , we already proved everything.  $\square$

*Remark.* Let  $M, N$  be continuous martingales null in 0 s.t.  $\mathbb{E}[\langle M \rangle_\infty] < \infty, \mathbb{E}[\langle N \rangle_\infty] < \infty$ , then  $MN - \langle M, N \rangle$  is a UI martingale.

**Definition 4.3** (Orthogonality). Two martingales are said to be orthogonal if  $\langle M, N \rangle = 0$ , i.e.  $MN$  is a local martingale.

**Theorem 4.11** (Kunita–Watanabe inequality). Let  $M, N$  be two continuous local martingales, and  $H, K$  two measurable processes  $(\mathbb{R}_+ \times \Omega, \mathcal{B}(\mathbb{R}_+) \otimes \mathcal{F}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ <sup>(5)</sup>, then

$$\begin{aligned} &\int_0^\infty |H_s| |K_s| |d\langle M, N \rangle_s| \\ &\leq \sqrt{\int_0^\infty H_s^2 d\langle M \rangle_s} \cdot \sqrt{\int_0^\infty K_s^2 d\langle N \rangle_s} \end{aligned}$$

*Proof.* In this proof we will use the notation  $\langle M, N \rangle_s^t := \langle M, N \rangle_t - \langle M, N \rangle_s$ ,  $s \leq t$ . Then with the Cauchy-Schwarz inequality we have (with theorem 4.7 and proposition 4.10 (iii)) for all  $s < t$ ,

$$|\langle M, N \rangle_s^t| \leq \sqrt{\langle M \rangle_s^t} \sqrt{\langle N \rangle_s^t},$$

a.s. Then (4.1) hold a.s. for all  $s < t \in \mathbb{Q}$ , and with the continuity  $\forall s < t \in \mathbb{R}$ . We will now fix  $\omega \in \Omega$  s.t. (4.1) is true.

Let us define  $s =: t_0 < \dots < t_p := t$  a subdivision,

$$\begin{aligned} \sum_{i=1}^p |\langle M, N \rangle_{t_{i-1}}^{t_i}| &\leq \sum_{i=1}^p \sqrt{\langle M \rangle_{t_{i-1}}^{t_i}} \sqrt{\langle N \rangle_{t_{i-1}}^{t_i}} \\ &\leq \sqrt{\sum_{i=1}^p \langle M \rangle_{t_{i-1}}^{t_i}} \sqrt{\sum_{i=1}^p \langle N \rangle_{t_{i-1}}^{t_i}} \\ &= \sqrt{\langle M \rangle_s^t \langle N \rangle_s^t}. \end{aligned}$$

By taking the supremum<sup>6</sup> on all the subdivisions of  $[s, t]$ ,

$$\int_{[s,t]} |d\langle M, N \rangle_u| \leq \sqrt{\langle M \rangle_s^t \langle N \rangle_s^t}.$$

(...)

#### 4.4 Continuous semimartingale

**Definition 4.4** (Semimartingale). A process  $(X_t, t \geq 0)$  is a continuous semimartingale if it can be written as

$$X_t = X_0 + M_t + V_t,$$

where  $M$  is a local continuous martingale,  $V$  is a continuous adapted v.f. process, and  $M_0 = V_0 = 0$  a.s.

*Remark.* We call this decomposition the (unique) canonical decomposition of  $X$ .

**Definition 4.5.** Let  $X_t = X_0 + M_t + V_t$ ,  $Y_t = Y_0 + N_t + W_t$  be two continuous semimartingales. We set

$$\langle X, Y \rangle_t := \langle M, N \rangle_t.$$

In particular  $\langle X \rangle_t = \langle M \rangle_t$ .

**Proposition 4.12.** Let  $X, Y$  be two continuous semimartingales, and  $0 =: t_0^n < \dots < t_{p_n}^n$  a sequence of subdivision where the intervals go to 0 as  $n \rightarrow \infty$ , then

$$\sum_{i=1}^{p_n} (X_{t_i^n} - X_{t_{i-1}^n}) (Y_{t_i^n} - Y_{t_{i-1}^n}) \xrightarrow[n \rightarrow \infty]{\mathbb{P}} \langle X, Y \rangle_t.$$

<sup>6</sup>Recall that

$$\sup_{t_i} \sum_{i=1}^p |a(t_i) - a(t_{i-1})| = \int_{[0,r]} |da|.$$

*Proof.* By polarisation we can prove the result with  $X = Y$ . Indeed,

$$\sum_{i=1}^{p_n} (X_{t_i^n} - X_{t_{i-1}^n})^2 = I_n + J_n + K_n,$$

with,

$$\begin{cases} I_n &= \sum_{i=1}^{p_n} (M_{t_i^n} - M_{t_{i-1}^n})^2 \\ J_n &= \sum_{i=1}^{p_n} (M_{t_i^n} - M_{t_{i-1}^n})^2 \\ K_n &= 2 \sum_{i=1}^{p_n} (M_{t_i^n} - M_{t_{i-1}^n}) (V_{t_i^n} - V_{t_{i-1}^n}). \end{cases}$$

we already have  $I_n \xrightarrow[n \rightarrow \infty]{\mathbb{P}} \langle M \rangle_t = \langle X \rangle_t$ . And

$$|J_n| \leq \underbrace{\max_{i=1}^{p_n} |V_{t_i^n} - V_{t_{i-1}^n}|}_{\xrightarrow{a.s.} 0} \underbrace{\sum_{i=1}^{p_n} |V_{t_i^n} - V_{t_{i-1}^n}|}_{\leq \int_0^t |dV_s| < \infty} \xrightarrow{a.s.} 0.$$

Same kind of proof for  $K_n$ . □

## □ 5 Stochastic integral

### 5.1 Integration for bounded integral in $L^2$

We will first recall some concepts:

- **Associativity:** let  $a : \mathbb{R}_+ \rightarrow \mathbb{R}$  continuous and variation finite,  $f : \mathbb{R}_+ \rightarrow \mathbb{R}$  measurable,  $\forall f$ ,  $\int_0^t |f(s)| |da(s)| < \infty$ . We also have  $b(t) := \int_0^t f(s) da(s)$  variation finite over  $\mathbb{R}_+$ . Then for all  $g : \mathbb{R}_+ \rightarrow \mathbb{R}$  measurable s.t.  $\forall t \geq 0$ ,  $\int_0^t |g(s)| |f(s)| |da(s)| < \infty$ ,  $\forall t \geq 0$

$$\int_0^t g(s) db(s) = \int_0^t g(s) f(s) da(s).$$

- **Integral stopping:**  $\forall T \geq 0$ ,  $\forall t \geq 0$ ,

$$\begin{aligned} \int_0^{T \wedge t} f(s) da(s) &= \int_0^t f(s) da(s \wedge T) \\ &= \int_0^t f(s) \mathbb{1}_{[0,T]}(s) da(s). \end{aligned}$$

- **Change of variable:**  $A, \alpha : \mathbb{R}_+ \rightarrow \mathbb{R}$  continuous, growing,  $A(0) = \alpha(0) = 0$ . Then for all  $f : \mathbb{R}_+ \rightarrow \mathbb{R}$  measurable,  $\forall t$ ,

$$\int_0^t f(\alpha(s)) dA(\alpha(s)) = \int_0^{\alpha(t)} f(u) dA(u).$$

We know define the filtered space  $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$ . We use the notation

$$\mathbb{H}^2 := \left\{ M : \text{cont. mart.}, \sup_{t \geq 0} \mathbb{E}[M_t^2] < \infty, M_0 = 0 \right\}$$

*Remark.* It is equivalent to  $\{M \text{ local martingale}, \mathbb{E}[\langle M \rangle_\infty] < \infty, M_0 = 0\}$  and  $M^2 - \langle M \rangle$  martingale UI.

We observe that for  $T$  stopping time,  $M \in \mathbb{H}^2 \Rightarrow M^T \in \mathbb{H}^2$ . And for all  $M, N \in \mathbb{H}^2$ ,

$$\begin{aligned} |\langle M, N \rangle_\infty| &\leq \int_0^\infty |d\langle M, N \rangle_s| \\ &\leq^{(KW)} \sqrt{\int_0^\infty d\langle M \rangle_s} \sqrt{\int_0^\infty d\langle N \rangle_s} \\ &= \sqrt{\langle M \rangle_\infty} \sqrt{\langle N \rangle_\infty}, \end{aligned}$$

hence,

$$\mathbb{E}[|\langle M, N \rangle_\infty|] \leq^{(CS)} \sqrt{\mathbb{E}[\langle M \rangle_\infty]} \sqrt{\mathbb{E}[\langle N \rangle_\infty]} < \infty.$$

We will note  $(M, N)_{\mathbb{H}^2} := \mathbb{E}[\langle M, N \rangle_\infty] \in \mathbb{R}$ . We see that  $(M, N)_{\mathbb{H}^2} = 0 \Rightarrow M = 0$ . Actually  $(M, N)_{\mathbb{H}^2}$  is a scalar product on  $\mathbb{H}^2$ . With the optimal stopping theorem we have  $(M, N)_{\mathbb{H}^2} = \mathbb{E}[M_\infty N_\infty]$ , and

$$\begin{aligned} \|M\|_{\mathbb{H}^2}^2 &:= (M, M)_{\mathbb{H}^2} \\ &= \mathbb{E}[\langle M \rangle_\infty] = \mathbb{E}[M_\infty^2]. \end{aligned}$$

**Proposition 5.1.**  $(\mathbb{H}^2, (\cdot, \cdot)_{\mathbb{H}^2})$  is an Hilbert space.

*Proof.* □

Now let us note, for all  $M \in \mathbb{H}^2$ ,

$$\begin{aligned} L^2(M) &:= \left\{ H \text{ prog. proc.} / \mathbb{E} \left[ \int_0^\infty H_s^2 d\langle M \rangle_s \right] < \infty \right\} \\ &= L^2(\mathbb{R}_+ \times \Omega, \mathcal{P}, d\mathbb{P} d\langle M \rangle_s). \end{aligned}$$

Let  $H, K \in L^2(M)$ , we define

$$(H, K)_{L^2(M)} := \mathbb{E} \left[ \int_0^\infty H_s K_s d\langle M \rangle_s \right].$$

**Theorem 5.2.** Let  $M \in \mathbb{H}^2, \forall H \in L^2(M), \exists! H \cdot M \in \mathbb{H}^2$  s.t.

$$\begin{aligned} \langle H \cdot M, N \rangle &= \underbrace{H \cdot \langle M, N \rangle}_{:= \left( \int_0^t H_s d\langle M, N \rangle_s, t \geq 0 \right)}, \end{aligned}$$

for all  $N \in \mathbb{H}^2$ .

The application

$$\begin{aligned} L^2(M) &\rightarrow \mathbb{H}^2 \\ H &\mapsto H \cdot M \end{aligned}$$

is an isometry (linear that preserves the norm).

We call  $H \cdot M = \left( (H \cdot M)_t := \int_0^t H_s dM_s, t \geq 0 \right)$  the stochastic integral (or Itô's integral).

*Proof.* □

**Proposition 5.3** (Associativity). Let  $M \in \mathbb{H}^2, K \in L^2(M)$ , we can then define  $H \in L^2(K \cdot M)$ . Then  $HK \in L^2(M)$ , we can define  $HK \cdot M \in L^2(M)$ , and

$$HK \cdot M = H \cdot (K \cdot M).$$

*Proof.* □

*Remark.* Then we can write

(i)

$$\int_0^t H_s (K_s dM_s) = \int_0^t H_s K_s dM_s.$$

(ii)  $\forall M, N \in \mathbb{H}^2, \forall H \in L^2(M), \forall K \in L^2(N)$ ,

$$\begin{aligned} \left\langle \int_0^\cdot H_s dM_s, N \right\rangle_t &= \int_0^t H_s d\langle M, N \rangle_s; \\ \left\langle \int_0^\cdot H_s dM_s, \int_0^\cdot K_s dN_s \right\rangle_t &= \int_0^t H_s K_s d\langle M, N \rangle_s; \\ \left\langle \int_0^\cdot H_s dM_s \right\rangle_t &= \int_0^t H_s^2 d\langle M \rangle_s. \end{aligned}$$

**Proposition 5.4.** Let  $M \in \mathbb{H}^2, H \in L^2(M)$  and  $T$  stopping time, then

$$\begin{aligned} (H \cdot M)^T &= H \cdot M^T \\ &= H \mathbb{1}_{[0, T]} \cdot M. \end{aligned}$$

*Proof.* □

## 5.2 Integration for continuous semimartingales

Let  $M$  be a continuous local martingale, we define

$$L_{loc}^2(M) := \left\{ H \text{ prog. proc.} / \mathbb{E} \left[ \int_0^\infty H_s^2 d\langle M \rangle_s \right] < \infty \right\}.$$

**Theorem 5.5.** Let  $M$  be a continuous local martingale,  $H \in L_{loc}^2(M)$ . Then

(i)  $\exists! H \cdot M$  continuous local martingale, null in zero s.t.

$$\langle H \cdot M, N \rangle = H \cdot \langle M, N \rangle,$$

for all  $N$  local martingale.

(ii) With  $T$  stopping time,  $H \cdot M^T = (H \cdot M)^T = H \mathbb{1}_{[0, T]} \cdot M$ .

(iii) If  $M \in \mathbb{H}^2, H \in L^2(M)$ , then  $H \cdot M$  is the Itô's integral defined in the last section.

*Proof.* □

*Remark.* With  $M$  continuous local martingale,  $H \in L_{loc}^2(M)$  and  $T$  stopping time,

(i) if  $\mathbb{E} \left[ \int_0^T H_s^2 d\langle M \rangle_s \right] < \infty$ , then

$$\begin{aligned} \mathbb{E} \left[ \int_0^T H_s dM_s \right] &= 0 ; \\ \mathbb{E} \left[ \left( \int_0^T H_s dM_s \right)^2 \right] &= \mathbb{E} \left[ \int_0^T H_s^2 d\langle M \rangle_s \right] ; \end{aligned}$$

(ii) if  $\forall t \geq 0$ ,  $\mathbb{E} \left[ \int_0^t H_s^2 d\langle M \rangle_s \right] < \infty$ , then  $\left( \int_0^t H_s dM_s \right)_{t \geq 0}$  is a continuous martingale square integrable, null in zero, s.t.  $\forall t \geq 0$ ,

$$\begin{aligned} \mathbb{E} \left[ \int_0^t H_s dM_s \right] &= 0 ; \\ \mathbb{E} \left[ \left( \int_0^t H_s dM_s \right)^2 \right] &= \mathbb{E} \left[ \int_0^t H_s^2 d\langle M \rangle_s \right]. \end{aligned}$$

We say that  $H$  is a process that is locally bounded if for all  $t$ ,

$$\sup_{s \in [0, t]} |H_s| < \infty \quad \text{a.s.}$$

**Definition 5.1.** Let  $X = X_0 + M + V$  be a continuous semimartingale, and  $H$  a progressive process locally bounded, then we define

$$H \cdot X := H \cdot M + H \cdot V.$$

*Remark.* Here  $H \cdot M$  is a local continuous martingale, null in 0. And  $H \cdot V$  is an adapted continuous process, with finite variations, null in 0.

**Proposition 5.6.** Here are few properties that we already saw. Let  $H, K$  progressive processes locally bounded, and  $X$  continuous semimartingale.

(i)  $H \cdot (K \cdot X) = HK \cdot X$ .

(ii) Let  $T$  be a stopping time, then  $(H \cdot X)^T = H \cdot X^T = H \mathbb{1}_{[0, T]} \cdot X$ .

(iii) If  $X$  is a continuous local martingale (or process with finite variations), then it is the same for  $H \cdot X$ .

(iv)  $(H, X) \mapsto H \cdot X$  is bilinear.

(v) Let  $H$  progressive s.t.  $H_s(\omega) = \sum_{i=0}^{p-1} H^{(i)}(\omega) \mathbb{1}_{]t_i, t_{i+1}]}(s)$ , where  $0 =: t_0 < \dots < t_p$ ,  $\forall i$   $H^{(i)}$  is  $(\mathcal{F}_{t_i})$ -measurable, then

$$(H \cdot X)_t = \sum_{i=0}^{p-1} H^{(i)}(X_{t_{i+1} \wedge t} - X_{t_i \wedge t}).$$

**Proposition 5.7.** Let  $X$  a continuous semimartingale and  $H$  a continuous adapted process, then  $\forall t > 0$ ,  $\forall 0 =: t_0^n < \dots < t_{p_n}^n := t$  where the interval goes to zero with  $n \rightarrow \infty$ ,

$$\int_0^t H_s dX_s \stackrel{\mathbb{P}}{=} \lim_{n \rightarrow \infty} \sum_{i=0}^{p_n-1} H_{t_i^n} (X_{t_{i+1}^n} - X_{t_i^n}).$$

*Proof.* □

*Remark.* We have to be careful, it's wrong to replace  $H_{t_i^n}$  by  $H_{t_{i+1}^n}$  or any other value in  $]H_{t_i^n}, H_{t_{i+1}^n}]$  in the equality.

**Proposition 5.8** (Integration by parts). Let  $X, Y$  continuous semimartingales, then

$$X_t Y_t = X_0 Y_0 + \int_0^t X_s dY_s + \int_0^t Y_s dX_s + \langle X, Y \rangle_t$$

for all  $t \geq 0$ .

*Proof.* □

*Remark.* With  $M$  local continuous martingale,

$$M_t^2 = M_0^2 + 2 \int_0^t M_s dM_s + \langle M \rangle_t.$$

## 6 Itô's formula and applications

### 6.1 Itô's formula

**Theorem 6.1** (Itô's formula). (i) (Unidimensional) Let  $X$  be a continuous semimartingale,  $f : \mathbb{R} \rightarrow \mathbb{R}$  in  $\mathcal{C}^2$ , then

$$\begin{aligned} f(X_t) &= f(X_0) + \int_0^t f'(X_s) dX_s \\ &\quad + \frac{1}{2} \int_0^t f''(X_s) d\langle X \rangle_s. \end{aligned}$$

(ii) (Multidimensional) Let  $X^1, \dots, X^N$  be continuous semimartingales,  $F : \mathbb{R}^N \rightarrow \mathbb{R}$  in  $\mathcal{C}^2$ ,

$$\begin{aligned} F(X_t) &= F(X_0) + \sum_{i=1}^N \int_0^t \frac{\partial F}{\partial x_i}(X_s) dX_s^i \\ &\quad + \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \int_0^t \frac{\partial^2 F}{\partial x_i \partial x_j}(X_s) d\langle X^i, X^j \rangle_s. \end{aligned}$$

*Proof.* □

*Remark.* (i) In the case  $F(x, y) := xy$  we found the formula of the integration by parts.

(ii) The Itô's formula is still true if  $(X_t, t \geq 0)$  with value in  $D \subset \mathbb{R}^N$  an open set (and convex), and if  $F : D \rightarrow \mathbb{R}$  in  $\mathcal{C}^2$ .

(iii) If  $X^1, \dots, X^k$  are continuous, adapted and with finite variations, the formula is still true if

$$F \in \mathcal{C}^{\overbrace{1, \dots, 1}^k, \overbrace{2, \dots, 2}^{N-k}}$$

(iv) The differential version is

$$df(X_t) = f'(X_t)dX_t + \frac{1}{2}f''(X_t)d\langle X \rangle_t$$

**Example 6.1** (Multidimensional brownian motion). We will note  $n \geq 1$  the dimension,  $(B := (B_t^{(1)}, \dots, B_t^{(n)}), t \geq 0)$  a  $(\mathcal{F}_t)$ -brownian motion in  $\mathbb{R}^n$  (hence  $B^{(1)}, \dots, B^{(n)}$  are independant  $\mathcal{F}_t$ -brownian motions).

Let us first see the case  $n = 1$ ,  $f : \mathbb{R} \rightarrow \mathbb{R}$  in  $\mathcal{C}^2$ ,

$$f(B_t) = f(0) + \int_0^t f'(B_s)dB_s + \frac{1}{2} \int_0^t f''(B_s)ds.$$

Now we take  $F : \mathbb{R}_+ \times \mathbb{R} \rightarrow \mathbb{R} \in \mathcal{C}^{1,2}$ , hence

$$\begin{aligned} F(t, B_t) &= F(0, 0) + \int_0^t \left( \frac{\partial F}{\partial s} + \frac{1}{2} \frac{\partial^2 F}{\partial x^2} \right) (s, B_s) ds \\ &\quad + \int_0^t \frac{\partial F}{\partial x} (s, B_s) dB_s. \end{aligned}$$

So if  $\frac{\partial F}{\partial t} + \frac{1}{2} \frac{\partial^2 F}{\partial x^2} = 0$  we have  $(F(t, B_t), t \geq 0)$  is a local martingale<sup>7</sup>. It is the case for  $F_1(t, x) = x$ ,  $F_2(t, x) = x^2 - t$ ,  $F_3(t, x) = x^3 - 3tx$ , etc. More generally

$$H_n(x) := (-1)^n e^{\frac{x^2}{2}} \frac{d^n}{dx^n} \left( e^{-\frac{x^2}{2}} \right);$$

$$H_n(x, t) := t^{\frac{n}{2}} H_n \left( \frac{x}{\sqrt{t}} \right) \quad (\text{mod. Hermite's poly.})$$

and then  $\forall n$ ,  $(H_n(B_t, t), t \geq 0)$  is a continuous local martingale. We also have, for all  $t \geq 0$ ,

$$\mathbb{E} \left[ \int_0^t \left| \frac{\partial H_n}{\partial x} (B_s, s) \right|^2 ds \right] < \infty$$

sp we know that  $\forall n$ ,  $(H_n(B_t, t), t \geq 0)$  is a martingale<sup>8</sup>.

More generally, if  $B$  is a  $(\mathcal{F}_t)$ -brownian motion in  $\mathbb{R}^n$ ,  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  in  $\mathcal{C}^2$ ,

$$\begin{aligned} F(B_t) &= F(0) + \sum_{i=1}^n \int_0^t \frac{\partial F}{\partial x_i} (B_s) dB_s^i \\ &\quad + \frac{1}{2} \int_0^t \Delta F(B_s) ds. \end{aligned}$$

## 6.2 Exponential semimartingale

**Theorem 6.2.** *Let  $X$  be a continuous semimartingale, then  $\exists ! Z$  continuous semimartingale s.t.*

$$Z_t = e^{X_0} + \int_0^t Z_s dX_s, \quad t \geq 0.$$

Moreover,

$$Z_T = \mathcal{E}(X)_t = e^{X_t - \frac{1}{2} \langle X \rangle_t}.$$

<sup>7</sup>Indeed we know that  $\int \cdot dB_s$  is a local martingale.

<sup>8</sup>Indeed recall that if  $\int_0^t H_s dM_s$  and if  $\forall t > 0$ ,  $\mathbb{E} \left[ \int_0^t H_s^2 d\langle M \rangle_s \right] < \infty$ , then  $(\int_0^t H_s dM_s, t \geq 0)$  is a martingale square integrable.

<sup>9</sup>Indeed recall that if  $M$  is a continuous positive supermartingale and  $\mathbb{E}[M_\infty] = \mathbb{E}[M_0]$ , then  $M$  is a martingale UI.

*Proof.* □

**Proposition 6.3.** *Let  $M$  be a continuous local martingale,  $\lambda \in \mathbb{C}$ , then*

$$\mathcal{E}(\lambda M)_t := \exp \left( \lambda M_t - \frac{\lambda^2}{2} \langle M \rangle_t \right),$$

$t \geq 0$ , is a continuous local martingale  $\mathbb{C}$ -valued.

*Proof.* □

Let  $L$  be a continuous local martingale,  $L_0 = 0$ . Then  $\mathcal{E}(L)_t$  is a positive continuous local martingale,  $\mathcal{E}(L)_0 = 1$ . Hence  $\mathcal{E}(L)$  is a positive supermartingale and with Fatou's Lemma  $\mathbb{E}[\mathcal{E}(L)_\infty] \leq 1$ . Now we want to know if  $\mathbb{E}[\mathcal{E}(L)_\infty] = 1$ , i.e.<sup>9</sup>  $\mathcal{E}(L)$  is a martingale UI.

**Theorem 6.4.** *Let  $L$  be a continuous local martingale,  $L_0 = 0$  a.s., then (i)  $\Rightarrow$  (ii)  $\Rightarrow$  (iii).*

$$(i) \text{ (Novikov)} \quad \mathbb{E} \left[ e^{\frac{1}{2} \langle L \rangle_\infty} \right] < \infty.$$

$$(ii) \text{ (Kazamaki)} \quad L \text{ continuous martingale UI, } \mathbb{E} \left[ e^{\frac{1}{2} L_\infty} \right] < \infty.$$

$$(iii) \quad \mathbb{E}[\mathcal{E}(L)_\infty] = 1.$$

*Proof.* □

## 6.3 Levy's characterization of the Brownian motion

We are in a filtered space  $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$ . Let  $B = (B^1, \dots, B^n)$  a  $\mathcal{F}_t$ -brownian motion  $\mathbb{R}^n$ -valued, then

$$\langle B^i, B^j \rangle_t = t \mathbb{1}_{\{i=j\}}.$$

**Theorem 6.5** (Levy). *(i)  $M$  continuous local martingale,  $M_0 = 0$  a.s., then*

$$\langle M \rangle_t = t, \quad \forall t \geq 0 \quad \Rightarrow \quad M \text{ is a } (\mathcal{F}_t)\text{-brownian motion.}$$

*(ii)  $M^1, \dots, M^n$  continuous local martingales null in 0, then*

$$\langle M^i, M^j \rangle_t = t \mathbb{1}_{\{i=j\}} \quad \Rightarrow \quad M \text{ is a } (\mathcal{F}_t)\text{-brownian motion } \mathbb{R}^n\text{-valued.}$$

*Proof.* □

**Example 6.2.** Let  $B$  a  $(\mathcal{F}_t)$ -brownian motion, and

$$\beta_t := \int_0^t \operatorname{sgn}(B_s) dB_s \quad t \geq 0,$$

then  $\beta$  is a continuous local martingale,  $\beta_0 = 0$ ,  $\langle \beta \rangle_t = \int_0^t \operatorname{sgn}^2(B_s) ds = t$ . And with Levy's Theorem  $\beta$  is a  $(\mathcal{F}_t)$ -brownian motion.

**Example 6.3.** Let  $(X, Y)$  two brownian motions  $\mathbb{R}^2$ -valued,  $X_0 = Y_0 = 0$ . For  $\theta \in \mathbb{R}$ ,

$$\begin{aligned} X_t^\theta &:= X_t \cos \theta - Y_t \sin \theta; \\ Y_t^\theta &:= X_t \sin \theta + Y_t \cos \theta, \quad t \geq 0. \end{aligned}$$

Hence  $X^\theta, Y^\theta$  are two continuous martingales null in 0 and  $\langle X^\theta \rangle_t = \langle Y^\theta \rangle_t = t$ ,  $\langle X^\theta, Y^\theta \rangle_t = 0$ , then  $(X^\theta, Y^\theta)$  is a brownian motion.

More generally let  $B$  a  $(\mathcal{F}_t)$ -brownian motion,  $A \in \mathcal{O}_n$ , then  $(AB_t, t \geq 0)$  is a brownian motion.

## 6.4 Dambis–Dubing–Schwarz Theorem

**Theorem 6.6** (Dambis–Dubing–Schwarz). *Let  $M$  be a continuous local martingale null in 0, then*

$$M_t = B_{\langle M \rangle_t}, \quad t \geq 0$$

with  $B$  a brownian motion.

*Proof.* □

*Remark.*  $B$  is not a  $(\mathcal{F}_t)$ -brownian motion but a  $(\mathcal{F}_{\tau_r})$ -brownian motion.

**Theorem 6.7** (Knight). *Let  $M^1, \dots, M^n$  continuous local martingales, null in 0,  $\langle M^i, M^j \rangle = 0$  for  $i \neq j$ , then*

$$\forall 1 \leq i \leq n, \quad M_t^i = B_{\langle M^i \rangle_t}^i, \quad t \geq 0,$$

$(B^1, \dots, B^n)$  is a brownian motion  $\mathbb{R}^n$ -valued.

## 6.5 Examples: multidimensional brownian motion

**Example 6.4.** Let  $M$  be a continuous local martingale,  $M_0 = 0$  a.s., then

- (i)  $\mathbb{P}\{\lim_{t \rightarrow \infty} |M_t| = \infty\} = 0$ .
- (ii)  $\{\lim_{t \rightarrow \infty} M_t \text{ exists (is finite)}\} = \{\langle M \rangle_\infty < \infty\} = \{\sup_{t \geq 0} M_t < \infty \text{ or } \inf_{t \geq 0} M_t > -\infty\}$  a.s.
- (iii)  $\{\langle M \rangle_\infty = \infty\} = \{\limsup_{t \rightarrow \infty} M_t = \infty, \liminf_{t \rightarrow \infty} M_t = -\infty\}$  a.s.

[Proof to be written]

<sup>10</sup>We have to be careful,  $M_0 = 1 \neq 0$ .

**Example 6.5** (Polar points and 2- $d$  brownian motion). Let  $(\beta, \gamma)$  be a brownian motion  $\mathbb{R}^2$ -valued,  $\beta_0 = \gamma_0 = 0$ . We define  $M_t = e^{\beta_t} \cos \gamma_t$ ,  $N_t = e^{\beta_t} \sin \gamma_t$ . With Itô we have

$$\begin{aligned} dM_t &= M_t d\beta_t - N_t d\gamma_t; \\ dN_t &= N_t d\beta_t + M_t d\gamma_t, \end{aligned}$$

so  $M, N$  are local martingales, and

$$\begin{aligned} d\langle M \rangle_t &= e^{2\beta_t} dt; \\ d\langle N \rangle_t &= e^{2\beta_t} dt; \\ d\langle M, N \rangle_t &= 0. \end{aligned}$$

Then with the Knight's Theorem<sup>10</sup>,  $(M_t - 1, N_t) = B_{\int_0^t e^{2\beta_s} ds}$  with  $B$  a brownian motion  $\mathbb{R}^2$ -valued. Let us take  $\omega \in \{\langle M \rangle_\infty\}$ , then  $\lim_{t \rightarrow \infty} M_t$  and  $\lim_{t \rightarrow \infty} N_t$  exist and are finite, hence  $\lim_{t \rightarrow \infty} (M_t^2 + N_t^2) = \lim_{t \rightarrow \infty} e^{2\beta_t}$  exists and is finite. So we conclude that  $\langle M \rangle_\infty = \infty$  a.s.,  $\int_0^\infty e^{2\beta_s} ds = \infty$  a.s. So we can write  $(M_t, N_t) = B_{\langle M \rangle_t} + (1, 0)$ , and as  $|(M_t, N_t)| = e^{\beta_t} > 0$ ,

$$\begin{aligned} \mathbb{P}\{\exists t \geq 0, B_{\langle M \rangle_t} = (-1, 0)\} &= 0 \\ \Rightarrow \mathbb{P}\{\exists s \geq 0, B_s = (-1, 0)\} &= 0 \\ \Rightarrow \forall a \in \mathbb{R}^2 \setminus \{0\}, \mathbb{P}\{\exists s \geq 0, B_s = a\} &= 0 \end{aligned}$$

with rotation and scaling.

**Example 6.6** (3- $d$  brownian motion). Let  $B$  be a brownian motion  $\mathbb{R}^3$ -valued, then  $\lim_{t \rightarrow \infty} |B_t| = \infty$  a.s.

To show that we just have to show that  $\forall x \in \mathbb{R}^3 \setminus \{0\}$ ,  $\lim_{t \rightarrow \infty} |B_t + x| = \infty$  a.s. We define  $Z_t := |B_t + x|^2 = \sum_{i=1}^3 (B_t^i + x_i)^2$ , and with Itô's formula,

$$\begin{aligned} dZ_t &= \sum_{i=1}^3 2(B_t^i + x_i) dB_t^i + \frac{1}{2} \sum_{i=1}^3 2 dt \\ &= 2 \sum_{i=1}^3 (B_t^i + x_i) dB_t^i + 3 dt. \end{aligned}$$

We define  $f : \mathbb{R}_+^* \rightarrow \mathbb{R}$ ,  $x \mapsto \frac{1}{\sqrt{x}}$ ,  $f \in \mathcal{C}^2$ , and  $Y_t := f(Z_t)$ , with Itô,

$$\begin{aligned} Y_t &= Y_0 - \frac{1}{2} \int_0^t \frac{1}{Z_s^{\frac{3}{2}}} dZ_s + \frac{1}{2} \frac{3}{4} \int_0^t \frac{1}{Z_s^{\frac{5}{2}}} d\langle Z \rangle_s \\ &= [\text{loc. mart.}] - \frac{3}{2} \int_0^t \frac{1}{Z_s^{\frac{3}{2}}} ds + \frac{3}{8} \int_0^t 2^2 \frac{Z_s}{Z_s^{\frac{5}{2}}} ds \\ &= [\text{loc. mart.}]. \end{aligned}$$

So  $Y$  is a positive local martingale and  $\mathbb{E}[Y_0] = \frac{1}{|x|} < \infty$ , hence  $Y$  is a positive supermartingale,  $\lim_{t \rightarrow \infty} Y_t = \xi \geq 0$  a.s. So  $\lim_{t \rightarrow \infty} |B_t + x| = \frac{1}{\xi}$  a.s., and we know that  $\limsup_{t \rightarrow \infty} |B_t + x| = \infty$  a.s., then  $\lim_{t \rightarrow \infty} |B_t + x| = \infty$  a.s.

**Example 6.7.** Let  $B$  be a brownian motion  $\mathbb{R}^n$ -valued,  $n \geq 2$ , with  $B_0 = x \in \mathbb{R}^n \setminus \{0\}$ . We set  $Z_t := |B_t|^2$ , hence,

$$dZ_t = 2 \sum_{i=1}^n B_t^i dB_t^i + n dt.$$

Now with  $f : \mathbb{R}_+^* \rightarrow \mathbb{R} \in \mathcal{C}^2$ ,  $Y_t := f(Z_t)$ ,

$$\begin{aligned} dY_t &= f'(Z_t) dZ_t + \frac{1}{2} f''(Z_t) d\langle Z \rangle_t \\ &= [\text{loc. mart.}] + n f'(Z_t) dt + \frac{1}{2} f''(Z_t) \times 4Z_t dt. \end{aligned}$$

So if  $f'(y) + \frac{2}{n} y f''(y) = 0$ ,  $\forall y \in \mathbb{R}_+^*$ , then  $Y$  is a local martingale. The following functions have this last property:

$$\begin{aligned} f(y) &:= \frac{1}{2} \ln y, & \text{for } n = 2, y > 0; \\ f(y) &:= y^{1-\frac{n}{2}}, & \text{for } n \geq 3, y > 0. \end{aligned}$$

Now we use the notation  $T_a := \inf\{t \geq 0 : |B_t| = a\}$ ,  $a > 0$ . And define  $0 < r < |x| < R$ , then  $(Y_{t \wedge T_R \wedge T_r}, t \geq 0)$  is a continuous bounded local martingale, so a martingale UI. With the optimal stopping theorem we have  $\mathbb{E}[f(Z_{T_R \wedge T_r})] = f(|x|^2)$ . With  $n = 2$ ,

$$\begin{aligned} &\mathbb{E}[\ln |B_{T_R \wedge T_r}|] = \ln |x| \\ \Leftrightarrow &\mathbb{E}[(\ln R) \mathbb{1}_{\{T_R < T_r\}}] + \mathbb{E}[(\ln r) \mathbb{1}_{\{T_r < T_R\}}] = \ln |x| \\ \Leftrightarrow &(\ln R) \mathbb{P}\{T_R < T_r\} + (\ln r) \mathbb{P}\{T_r < T_R\} = \ln |x| \\ \Leftrightarrow &\mathbb{P}\{T_r < T_R\} = \frac{\ln R - \ln |x|}{\ln R - \ln r}. \end{aligned}$$

So with  $R \rightarrow \infty$ ,  $\mathbb{P}\{T_r < \infty\} = 1$ .

Now with  $n \geq 3$

$$\begin{aligned} &\mathbb{E}[|B_{T_R \wedge T_r}|^{2-n}] = |x|^{2-n} \\ \Leftrightarrow &R^{2-n} \mathbb{P}\{T_R < T_r\} + r^{2-n} \mathbb{P}\{T_r < T_R\} = |x|^{2-n} \\ \Leftrightarrow &\mathbb{P}\{T_r < T_R\} = \frac{|x|^{2-n} - R^{2-n}}{r^{2-n} - R^{2-n}}, \end{aligned}$$

with  $R \rightarrow \infty$ ,  $\mathbb{P}\{T_r < \infty\} = \left(\frac{r}{|x|}\right)^{n-2} < 1$ .

## 6.6 Burkholder–Davis–Gundy inequality

We are in the filtered space  $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$ . And for  $X$  process, we use the notation

$$X_t^* := \sup_{s \in [0, t]} |X_s|, \quad \forall t \in \mathbb{R}_+ \cup \{\infty\}.$$

**Theorem 6.8** (Burkholder–Davis–Gundy). *Let  $p \in \mathbb{R}_+^*$ , then  $\exists 0 < c_p \leq C_p < \infty$  s.t.  $\forall M$  continuous local martingale,  $M_0 = 0$  a.s.,*

$$c_p \mathbb{E} \left[ \langle M \rangle_\infty^{\frac{p}{2}} \right] \leq \mathbb{E}[(M_\infty^*)^p] \leq C_p \mathbb{E} \left[ \langle M \rangle_\infty^{\frac{p}{2}} \right].$$

And in particular,  $\forall T$  stopping time,

$$c_p \mathbb{E} \left[ \langle M \rangle_T^{\frac{p}{2}} \right] \leq \mathbb{E}[(M_T^*)^p] \leq C_p \mathbb{E} \left[ \langle M \rangle_T^{\frac{p}{2}} \right].$$

**Lemma 6.9.** *Let  $B$  be a  $(\mathcal{F}_t)$ -brownian motion,  $T$  a stopping time,  $\beta > 1$ ,  $\delta > 0$ ,  $x > 0$ , then*

$$\begin{aligned} \mathbb{P} \left\{ B_T^* > \beta x, \sqrt{T} \leq \delta x \right\} &\leq \frac{\delta^2}{(\beta - 1)^2} \mathbb{P} \{ B_T^* \geq x \}; \\ \mathbb{P} \left\{ \sqrt{T} > \beta x, B_T^* \leq \delta x \right\} &\leq \frac{\delta^2}{\beta^2 - 1} \mathbb{P} \left\{ \sqrt{T} \geq x \right\}. \end{aligned}$$

**Lemma 6.10.** *Let  $\xi \geq 0$ ,  $\eta \geq 0$ , r.v. s.t.*

$$\mathbb{P}\{\xi > 2x, \eta \leq \delta x\} \leq \delta^2 \mathbb{P}\{\xi \geq x\}, \quad \forall \delta, x > 0,$$

then,  $\forall p > 0$ ,  $\exists c(p) < \infty$  s.t.

$$\mathbb{E}[\xi^p] \leq c(p) \mathbb{E}[\eta^p].$$

*Proof.* (Theorem 6.8) □

*Proof.* (Lemma 6.9) □

*Proof.* (Lemma 6.10) □

**Example 6.8.** Let  $M$  be a continuous local martingale,  $M_0 = 0$  a.s.,

$$\begin{aligned} \mathbb{E}[\langle M \rangle_\infty] < \infty &\Leftrightarrow \mathbb{E}[(M_\infty^*)^2] < \infty \quad (\text{BDG}) \\ &\Leftrightarrow M \text{ martingale bounded in } L^2. \end{aligned}$$

**Example 6.9** (Wald identities). Let  $B$  be a  $(\mathcal{F}_t)$ -brownian motion,  $T$  a stopping time,

$$\begin{aligned} \mathbb{E}[\sqrt{T}] < \infty &\Leftrightarrow \mathbb{E}[\underbrace{B_T^*}_{=(B^T)_\infty}] < \infty \quad (\text{BDG}) \\ &\Rightarrow B^T \text{ martingale UI} \\ &\Rightarrow \mathbb{E}[B_T] = \mathbb{E}[B_0] = 0 \quad (\text{Opt. stopping}) \end{aligned}$$

$$\begin{aligned} \mathbb{E}[T] < \infty &\Leftrightarrow \mathbb{E}[(B_T^*)^2] < \infty \quad (\text{BDG}) \\ &\Rightarrow B^T, ((B_t^T)^2 - (T \wedge t), t \geq 0) \text{ mart. UI} \\ &\Rightarrow \mathbb{E}[B_T^2 - T] = 0 \\ &\Rightarrow \mathbb{E}[B_T^2] = \mathbb{E}[T]. \end{aligned}$$

## 6.7 Martingales of a brownian filtration

We are in the complete probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . Let  $B$  be a brownian motion. And we set  $(\mathcal{F}_t)$  (the usually augmentation of) the canonical filtration of  $B$ .

**Theorem 6.11.** *Let  $(\mathcal{F}_t)$  be (the usually augmentation of) the canonical filtration of  $B$ , then for all  $M$  continuous local martingale, there exists a unique constant  $c$  and a progressive process  $(H_t, t \geq 0)$  s.t.  $\forall t > 0$ ,  $\int_0^t H_s^2 ds < \infty$  a.s., s.t.*

$$M_t = c + \int_0^t H_s dB_s.$$

If moreover  $M$  is a continuous martingale with  $\sup_{t \geq 0} \mathbb{E}[M_t^2] < \infty$  then

$$\mathbb{E} \left[ \int_0^\infty H_s^2 ds \right] < \infty.$$



## 6.8 Girsanov theorem

We are in the filtered space  $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$ .

**Theorem 6.12** (Girsanov). *Define  $(L_t, t \geq 0)$  a continuous local martingale,  $L_0 = 0$  a.s. Assume that  $\mathbb{E}[\mathcal{E}(L)_\infty] = 1$  (i.e.  $\mathcal{E}(L)$  is a martingale UI). Let  $\mathbb{Q}$  be a probability measure on  $(\Omega, \mathcal{F}_\infty)$  defined by  $\mathbb{Q} := \mathcal{E}(L)_\infty \cdot \mathbb{P}$  (i.e.  $\forall A \in \mathcal{F}_\infty, \mathbb{Q} = \mathbb{E}[\mathcal{E}(L)_\infty \mathbb{1}_A]$ ). Then for all  $M$  local continuous  $\mathbb{P}$ -martingale,*

$$M - \langle M, L \rangle$$

is a local continuous  $\mathbb{Q}$ -martingale.

*Proof.*

*Remark.* (i)  $\mathbb{Q} \ll \mathbb{P}$  on  $\mathcal{F}_\infty$ , but not the inverse. And we have  $\forall t \geq 0, \mathbb{Q} \sim \mathbb{P}$  on  $\mathcal{F}_t$ .

(ii) If  $X$  is a  $\mathbb{P}$ -semimartingale, it's also a  $\mathbb{Q}$ -semimartingale.

(iii) A result  $\mathbb{P}$ -a.s. or in probability hold un  $\mathbb{Q}$ .

(iv) Set  $B$  a  $(\mathcal{F}_t)$ -brownian motion under  $\mathbb{P}$ , then  $B - \langle B, L \rangle$  is a  $(\mathcal{F}_t)$ -brownian motion under  $\mathbb{Q}$ .

**Theorem 6.13** (Girsanov, horizon finite version). *For  $t > 0$ , let  $(L_s, s \in [0, t])$  be a continuous local martingale,  $L_0 = 0$  a.s. Assume that  $\mathbb{E}[e^{L_t - \frac{1}{2}\langle L \rangle_t}] = 1$ . Let  $\mathbb{Q}$  on  $(\Omega, \mathcal{F}_t)$  be the probability measure defined by  $\mathbb{Q} = e^{L_t - \frac{1}{2}\langle L \rangle_t} \cdot \mathbb{P}$ . Then for all  $M$  local  $\mathbb{P}$ -martingale, the process  $(M_s - \langle M, L \rangle_s, s \in [0, t])$  is a local  $\mathbb{Q}$ -martingale.*

**Example 6.10** (Cameron–Martin). Let  $h : \mathbb{R}_+ \rightarrow \mathbb{R}$  measurable s.t.  $\forall t, \int_0^t h^2(s) ds < \infty$ . We define  $L_t := \int_0^t h(s) dB_s, t \geq 0$ . Then  $(\mathcal{E}(L)_t, t \geq 0)$  is a positive supermartingale and as  $\mathbb{E}[e^{\frac{1}{2}\langle L \rangle_t}] < \infty, \forall t > 0, (\mathcal{E}(L)_s, s \in [0, t])$  is a martingale UI.

There exists<sup>11</sup> a probability  $\mathbb{Q}$  s.t.  $\forall t, \mathbb{Q}|_{\mathcal{F}_t} = \mathcal{E}(L)_t \cdot \mathbb{P}|_{\mathcal{F}_t}$ . With the Girsanov theorem  $\forall t \geq 0, (B_s - \int_0^t h(u) du, s \in [0, t])$  is a  $\mathbb{Q}$ -brownian motion. Then  $(B_s - \int_0^t h(u) du, s \geq 0)$  is a  $\mathbb{Q}$ -brownian motion.

In particular let  $h(t) = \gamma \in \mathbb{R}$ , then  $\mathbb{Q}|_{\mathcal{F}_t} = e^{\gamma B_t - \frac{1}{2}\gamma^2 t} \cdot \mathbb{P}|_{\mathcal{F}_t}$ . The process  $(B_t - \gamma t, t \geq 0)$  is a  $\mathbb{Q}$ -brownian motion and then  $B$  under  $\mathbb{Q}$  is a brownian motion with drift  $\gamma$ .

We are looking at  $T_a := \inf\{t \geq 0 : B_t = a\}$ , for all

$t \geq 0$ ,

$$\begin{aligned} \mathbb{Q}\{T_a \leq t\} &= \mathbb{E}\left[e^{\gamma B_t - \frac{1}{2}\gamma^2 t} \mathbb{1}_{\{T_a \leq t\}}\right] \\ &= \mathbb{E}\left[\mathbb{E}\left[e^{\gamma B_t - \frac{1}{2}\gamma^2 t} \mathbb{1}_{\{T_a \leq t\}} \middle| \mathcal{F}_{T_a \wedge t}\right]\right] \\ &= \mathbb{E}\left[\mathbb{1}_{\{T_a \leq t\}} \mathbb{E}\left[e^{\gamma B_t - \frac{1}{2}\gamma^2 t} \middle| \mathcal{F}_{T_a \wedge t}\right]\right] \\ &= \mathbb{E}\left[\mathbb{1}_{\{T_a \leq t\}} e^{\gamma B_{T_a \wedge t} - \frac{1}{2}\gamma^2 (T_a \wedge t)}\right] \\ &= \mathbb{E}\left[\mathbb{1}_{\{T_a \leq t\}} e^{\gamma a - \frac{1}{2}\gamma^2 (T_a \wedge t)}\right], \quad T_a \sim \frac{a^2}{B_1^2} \\ &= \int_0^t e^{\gamma a - \frac{1}{2}\gamma^2 s} \frac{|a|}{\sqrt{2\pi s^3}} e^{-\frac{a^2}{2s}} ds \\ &= \int_0^t \frac{|a|}{\sqrt{2\pi s^3}} e^{-\frac{(\gamma s - a)^2}{2s}} ds. \end{aligned}$$

□ Now  $t \rightarrow \infty$ ,

$$\begin{aligned} \mathbb{Q}\{T_a \leq t\} &= \mathbb{E}\left[e^{\gamma a - \frac{1}{2}\gamma^2 T_a} \underbrace{\mathbb{1}_{\{T_a \leq \infty\}}}_{= 1 \text{ } \mathbb{P}\text{-a.s.}}\right] \\ &= e^{\gamma a} \underbrace{\mathbb{E}\left[e^{-\frac{1}{2}\gamma^2 T_a}\right]}_{= e^{-|\gamma||a|}} \\ &= \begin{cases} 1 & \text{if } \gamma a \geq 0; \\ e^{2\gamma a} & \text{else.} \end{cases} \end{aligned}$$

## 7 Stochastic differential equations

### 7.1 Strong and weak solutions

**Definition 7.1** (Stochastic differential equations). Let  $d, m \geq 1$ , the applications

$$\begin{aligned} \sigma : \mathbb{R}_+ \times \mathbb{R}^d &\rightarrow \mathcal{M}_{d,m}(\mathbb{R}); \\ b : \mathbb{R}_+ \times \mathbb{R}^d &\rightarrow \mathbb{R}^d. \end{aligned}$$

are measurable and locally bounded. We define the SDE  $E(\sigma, b)$

$$dX_t = \sigma(t, X_t) dB_t + b(t, X_t) dt.$$

We say that  $E(\sigma, b)$  has a solution if there exists:

- $(\Omega, \mathcal{F}(\mathcal{F}_t), \mathbb{P})$  filtered space,
- $B = (B^1, \dots, B^m)$   $(\mathcal{F}_t)$ -brownian motion  $\mathbb{R}^m$ -valued,
- $X = (X^1, \dots, X^d)$  continuous adapted process s.t.

$$X_t = X_0 + \int_0^t \sigma(s, X_s) dB_s + \int_0^t b(s, X_s) ds.$$

In the special case where  $X_0 = x \in \mathbb{R}^d$ , we say that  $(\Omega, \mathcal{F}(\mathcal{F}_t), \mathbb{P}, B, X)$  is a solution of  $E_x(\sigma, b)$ .

**Definition 7.2.** (i) The weak existence of  $E(\sigma, b)$  means that for all  $x \in \mathbb{R}^d$ , there exists a solution for  $E_x(\sigma, b)$ .

<sup>11</sup>This result is given by the theorem of Kolmogorov.

- (ii) The weak uniqueness for  $E(\sigma, b)$  means that  $\forall x \in \mathbb{R}^d$ , all the solutions for  $E_x(\sigma, b)$  have the same law.

**Example 7.1.** Let  $dX_t = \text{sgn}(X_t) dB_t$ . For a fixed  $x \in \mathbb{R}$ ,  $\forall (\Omega, \mathcal{F}(\mathcal{F}_t), \mathbb{P})$ ,  $\beta$  a  $(\mathcal{F}_t)$ -brownian motion,  $\beta_0 = x$ . And we define

$$B_t := \int_0^t \text{sgn}(\beta_s) d\beta_s.$$

Then  $\langle B \rangle_t = \int_0^t 1 ds = t$ , and by Levy  $B$  is a  $(\mathcal{F}_t)$ -brownian motion. And then

$$\begin{aligned} dB_t &= \text{sgn}(\beta_t) d\beta_t \\ \Leftrightarrow d\beta_t &= \text{sgn}(\beta_t) dB_t. \end{aligned}$$

**Example 7.2.** Let  $dX_t = dB_t + b(t, X_t) dt$ . For all  $(\Omega, \mathcal{F}(\mathcal{F}_t), \mathbb{P})$ ,  $\forall X$   $(\mathcal{F}_t)$ -brownian motion, let  $\mathbb{Q}$  be a probability measure s.t.

$$\mathbb{Q}|_{\mathcal{F}_t} = \exp\left(\int_0^t b(s, X_s) dX_s - \frac{1}{2} \int_0^t b(s, X_s)^2 ds\right) \cdot \mathbb{P}|_{\mathcal{F}_t}$$

so with Girsanov,  $B_t := X_t - \int_0^t b(s, X_s) ds$  is a  $(\mathcal{F}_t)$ -brownian motion under  $\mathbb{Q}$ . So  $(\Omega, \mathcal{F}(\mathcal{F}_t), \mathbb{Q}, B, X)$  is a solution.

**Definition 7.3.** (i) Strong uniqueness for  $E(\sigma, b)$  if two solution  $X$  and  $\tilde{X}$  associated to the same filtered space and the same brownian motion s.t.  $X_0 = \tilde{X}_0$  a.s. are indistinguishable.

- (ii) We fix  $(\Omega, \mathcal{F}(\mathcal{F}_t), \mathbb{P})$  and  $B$   $(\mathcal{F}_t)$ -brownian motion. We say that  $X$  is a strong solution for  $E(\sigma, b)$  if  $X$  is adapted according to the canonical filtration of  $B$ .

**Example 7.3.** We retake the SDE  $dX_t = \text{sgn}(X_t) dB_t$ . There is no strong uniqueness, indeed if  $X$  is solution with  $X_0 = 0$ , then  $-X$  is also solution.

**Example 7.4.** Consider the SDE

$$dX_t = \lambda X_t dB_t,$$

with  $\lambda \in \mathbb{R}$ . We know from Theorem 6.2 that there is strong uniqueness and for all  $x$  the solution is  $X_t = x \exp(\lambda B_t - \frac{1}{2} \lambda^2 t)$ .

**Theorem 7.1** (Yamada–Watanabe). *If there is weak existence and strong uniqueness then there is weak uniqueness.*